

Last time: a (left) action of a group G
on a set X .

needs to satisfy $g \cdot (h \cdot x) = (gh) \cdot x$
and $1 \cdot x = x$

The orbit of an element $x \in X$ is

$$\mathcal{O}_x = \{ g \cdot x \mid g \in G \} \subset X$$

The stabilizer of x is

$$G_x = \{ g \mid gx = x \} \subset G$$

it's a subgroup: if $g, h \in G_x$
then $(gh) \cdot x = g \cdot (h \cdot x) = g \cdot x = x$
so $gh \in G_x$

$$\text{and } g^{-1} \cdot x = g^{-1} \cdot (g \cdot x) = (gg^{-1}) \cdot x \\ = 1 \cdot x = x$$

so $g^{-1} \in G_x$ □

Soon: the orbit-stabilizer theorem:

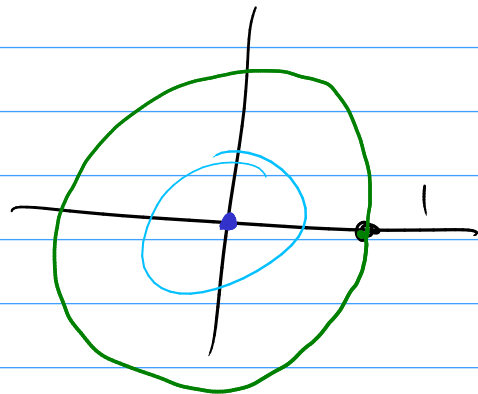
$$|\mathcal{O}_x| \cdot |G_x| = |G|$$

$$\left(\begin{array}{l} \# \text{ elements in} \\ \mathcal{O}_x \end{array} \cdot \begin{array}{l} \# \text{ elements in} \\ G_x \end{array} = \begin{array}{l} \# \text{ elements} \\ \text{in } G. \end{array} \right)$$

Examples: \mathbb{R} acts on \mathbb{C} by rotations

$$t \cdot z = e^{it} z$$

orbit of $1 \in \mathbb{C}$
is $\{e^{it} \cdot 1 \mid t \in \mathbb{R}\}$
= unit circle



stabilizer of 1 is

$$\{t \in \mathbb{R} \mid e^{it} = 1\}$$

$$= \{2\pi n \mid n \in \mathbb{Z}\} = \{0, \pm 2\pi, \pm 4\pi, \dots\}$$

subgroup of \mathbb{R} under addition.

orbit of 0 is $\{0\}$

stabilizer is all of \mathbb{R}

$$e^{it} \cdot 0 = 0 \quad \forall t$$

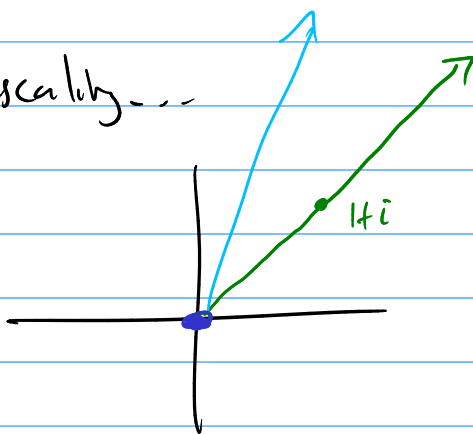
example: \mathbb{R} acts on \mathbb{C} by rescaling...

$$t \cdot z = e^t z$$

orbits are rays

orbit of $1+i$ is

$$\{e^t \cdot (1+i) \mid t \in \mathbb{R}\}$$



stabilizer of $1+i$ is $\{0\}$:

if $e^t \cdot (1+i) = (1+i)$ then $e^t = 1$ so $t = 0$

orbit of 0 is $\{0\}$

stabilizer of 0 is all of \mathbb{R}

An element $x \in X$ is a fixed point for the action of G if

$$g \cdot x = x \quad \forall g \in G.$$

eg. the origin in the two actions above.

General Linear Group

Example: $GL_3(\mathbb{R}) =$ 3×3 invertible matrices

$$A = \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \quad \left| \quad \det A \neq 0 \right.$$

group of units in $M_{3 \times 3}(\mathbb{R})$

(ring of all 3×3 matrices)

acts on \mathbb{R}^3 : $A \cdot \vec{v} = A\vec{v}$.

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} ax + by + cz \\ dx + ey + fz \\ gx + hy + iz \end{pmatrix}$$

is it an action?

$$A \cdot (B \cdot v) = (AB) \cdot v \quad \checkmark$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad \checkmark$$

orbit of $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$:

$$\begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} a \\ d \\ g \end{pmatrix}$$

get any non-zero

vector this way.

$$\text{stabilizer of } \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}: \left\{ \begin{pmatrix} 1 & b & c \\ 0 & e & f \\ 0 & h & i \end{pmatrix} \in GL_3(\mathbb{R}) \right\}$$

$\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ is a fixed point.

Orbit-Stabilizer Theorem

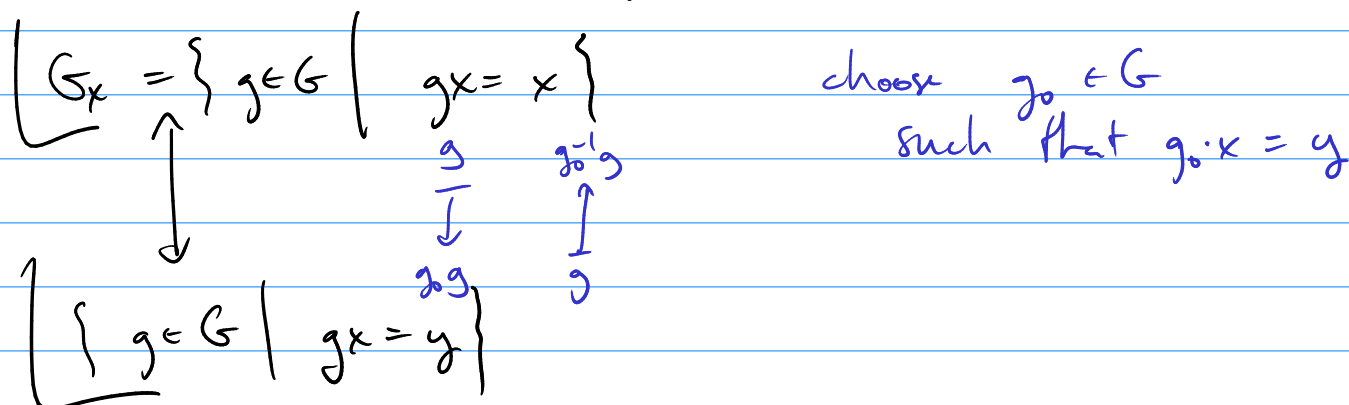
a group G acts on a set X .

for any $x \in X$, $|O_x| \cdot |G_x| = |G|$

Proof: first assume $|O_x|$ and $|G_x|$ are finite

$$|G| = \sum_{y \in O_x} \# \text{g's in } G \text{ that take } x \text{ to } y. \\ \# \{g \in G \mid gx = y\} \rightarrow \text{all the same size as } G_x$$

I claim that for any $y \in O_x$, there is a bijection



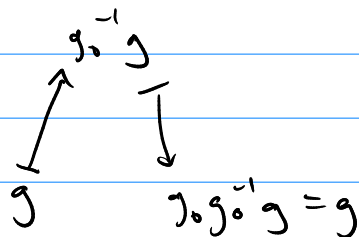
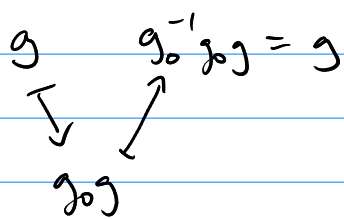
if $gx = x$ then $(g_0 g) \cdot x = g_0(gx) = g_0 x = y$

if $gx = y$ then $(g_0^{-1} g) = g_0^{-1}(gx) = g_0^{-1} y$

$$= g_0^{-1}(g_0 x) = (g_0^{-1} g_0) x$$

$$= 1 \cdot x = x.$$

these two maps are inverse bijections:



Infinite case: less interesting. Think about it.