

## Solutions to Homework 4

1. If  $f: X \rightarrow Y$  is a submersion and  $U$  is an open set of  $X$ , show that  $f(U)$  is open in  $Y$ .

The point is that the projection  $\mathbb{R}^k \rightarrow \mathbb{R}^l$ , where  $k \geq l$ , is an open map, and if a map is “locally open” then it is open.

Let  $k = \dim X$  and  $l = \dim Y$ . By the local submersion theorem, for each  $x \in X$  there is a parametrization  $\phi_x: U_x \rightarrow X$ , where  $U_x \subset \mathbb{R}^k$  and  $\phi_x(0) = x$ , and a parametrization  $\psi_x: V_x \rightarrow Y$ , where  $V_x \subset \mathbb{R}^l$  and  $\psi_x(0) = f(x)$ , such that  $f(\phi_x(U_x)) \subset \psi_x(V_x)$  and

$$(\psi_x^{-1} \circ f \circ \phi_x)(x_1, \dots, x_k) = (x_1, \dots, x_l).$$

First observe this is an open map: an open set in  $U_x \subset \mathbb{R}^k$  is a union of open boxes  $(a_1, b_1) \times \dots \times (a_k, b_k)$ , so its image in  $V_x \subset \mathbb{R}^l$  is a union of open boxes  $(a_1, b_1) \times \dots \times (a_l, b_l)$ , hence is open.

Next observe that

$$f \circ \phi_x: U_x \rightarrow Y$$

is an open map, because it is a composition of two open maps  $\psi_x$  and  $\psi_x^{-1} \circ f \circ \phi_x$ .

Now suppose that  $U \subset X$  is open. The open sets  $\phi_x(U_x)$  cover  $X$ , so

$$U = \bigcup_{x \in X} U \cap \phi_x(U_x) = \bigcup_{x \in X} \phi_x(\phi_x^{-1}(U)),$$

so

$$f(U) = \bigcup_{x \in X} f(\phi_x(\phi_x^{-1}(U)))$$

is a union of open sets, hence is open.

12. Prove that the set of all  $2 \times 2$  matrices of rank 1 is a 3-dimensional submanifold of  $\mathbb{R}^4 = M(2)$ .

Recall that a  $2 \times 2$  matrix  $A$  has rank 1 if and only if  $\det A = 0$  and  $A \neq 0$ . We compute the critical points of the determinant map  $M(2) \rightarrow \mathbb{R}$ , given by

$$\det \begin{pmatrix} x & y \\ z & w \end{pmatrix} = xw - yz.$$

Its derivative is

$$d \det_{(x,y,z,w)} = (w \quad -z \quad -y \quad x),$$

which vanishes only at the origin. Thus the restriction of  $\det$  to  $M(2) \setminus 0$  is a submersion, so the preimage of 0, which is the set we want, is a submanifold of dimension  $4 - 1 = 3$ .

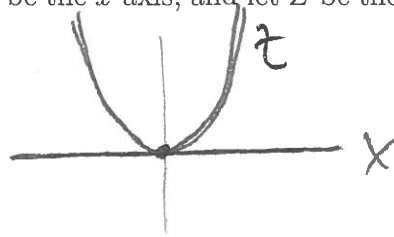
2. Which of the following linear spaces intersect transversely?

Looking at problem 1, we see that two subspaces are transverse if and only if they span the ambient space.

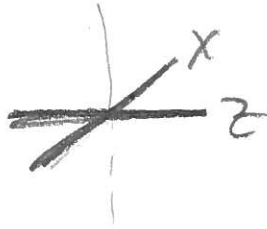
- (a) The  $xy$ -plane and the  $z$ -axis in  $\mathbb{R}^3$  are transverse.
- (b) The  $xy$ -plane and the plane spanned by  $(3, 2, 0)$  and  $(0, 4, -1)$  in  $\mathbb{R}^3$  are transverse.
- (c) The plane spanned by  $(1, 0, 0)$  and  $(2, 1, 0)$  and the  $y$ -axis in  $\mathbb{R}^3$  are not transverse: the plane contains the line.
- (d)  $\mathbb{R}^k \times \{0\}$  and  $\{0\} \times \mathbb{R}^l$  in  $\mathbb{R}^n$ : we must interpret the first 0 as being in  $\mathbb{R}^{n-k}$  and the second as being in  $\mathbb{R}^{n-l}$ . Then the two are transverse if and only if  $k + l \geq n$ .
- (e)  $\mathbb{R}^k \times \{0\}$  and  $\mathbb{R}^l \times \{0\}$  in  $\mathbb{R}^n$  are transverse if and only if  $k = n$  or  $l = n$ .
- (f)  $V \times \{0\}$  and the diagonal in  $V \times V$  are transverse: let  $(v, w) \in V \times V$  be given; then  $(v, w) = (v - w, 0) + (w, w)$ .
- (g) Symmetric and skew-symmetric matrices in  $M(n)$  are transverse: let  $A \in M(n)$  be given; then  $\frac{A^\top + A}{2}$  is symmetric, and  $\frac{A^\top - A}{2}$  is skew-symmetric, and their sum is  $A$ .

6. Suppose that  $X$  and  $Z$  do not intersect transversally in  $Y$ . May  $X \cap Z$  still be a manifold? If so, must its codimension still be  $\text{codim } X + \text{codim } Z$ ? (Can it be?)

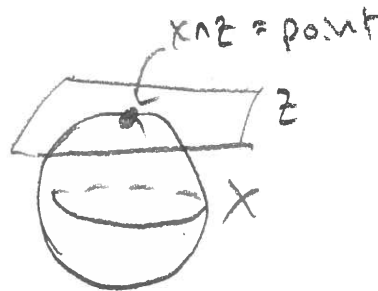
$X \cap Z$  may be a manifold of the expected dimension: for example, let  $Y = \mathbb{R}^2$ , let  $X$  be the  $x$ -axis, and let  $Z$  be the parabola  $y = x^2$ .



It may be a manifold of greater-than-expected dimension: for example, let  $Y = \mathbb{R}^3$ , let  $X$  be the  $x$ -axis, and let  $Z$  be the  $y$ -axis.



It may be a manifold of less-than-expected dimension: for example, let  $Y = \mathbb{R}^3$ , let  $X$  be the sphere  $x^2 + y^2 + z^2 = 1$ , and let  $Z$  be the plane  $z = 1$ .



(Interestingly, this last behavior can only occur with real manifolds, not with complex manifolds: if we write the same equations in  $\mathbb{C}^3$ , the intersection has the expected dimension, although it is not smooth.)