

# More about exponentiating

We saw this in proof of Serre's theorem. In fact it's a foundational principle.

Let  $x: V \rightarrow V$ . Then  $\exp(x) = 1 + x + \frac{x^2}{2!} + \dots : V \rightarrow V$

nilpotent  
linear map

f.d. vector space

Makes sense as actually finite sum

[If over  $\mathbb{R}$  or  $\mathbb{C}$  don't need  
nilpotency ... convergence]

Let  $y: V \rightarrow V$  be another such.

Suppose  $x$  and  $y$  commute. Then

$$\exp(x) \circ \exp(y) = \exp(x+y)$$

follows from formal property of  
exponential power series

← algebra  
binomial theorem ex.

analysis → laws of  
exponential

This implies  $\exp(x) \in \cancel{GL}(V)$   
SL

$$\text{as } \exp(x)^{-1} = \exp(-x)$$

It's a nilpotent linear map — all  
its eigenvalues are 1  $\begin{pmatrix} 1 & * \\ 0 & 1 \end{pmatrix}$

- If  $V$  is an algebra  $A$  and  $x: A \rightarrow A$  is a derivation then  $\exp(x): A \rightarrow A$  is an algebra automorphism.

$$\begin{aligned} \left(1 + x + \frac{x^2}{2!} + \dots\right)(ab) &= ab + x(a)b + ax(b) + \frac{x^2}{2!}(a)b + x(a)x(b) + a\frac{x^2}{2!}(b) + \dots \\ &= \left(a + x(a) + \frac{x^2}{2!}(a) + \dots\right)\left(b + x(b) + \frac{x^2}{2!}(b) + \dots\right) = \dots \end{aligned}$$

$\Rightarrow \text{ad } x$  is nilpotent

- If  $x, y \in \mathfrak{g} \leq \mathfrak{gl}(V)$ ,  $V$  f.d.,  $x$  nilpotent

$$\exp(x) y \exp(x)^{-1} = \exp(\text{ad } x)(y)$$

$$\Rightarrow \text{Ad}(\exp x) = \exp(\text{ad } x)$$

$$\text{in } \text{Inn}(\mathfrak{g}) \cong \text{Aut}(\mathfrak{g})$$

$$\text{ad } x = \lambda_x - \rho_x \quad \text{left/right mult. by } x, \text{ commute}$$

$$\therefore \exp(\text{ad } x) = \exp(\lambda_x) \circ \exp(\rho_x)^{-1}$$

$\uparrow$   
Lie alg.-autos.

Example 1  $\mathfrak{g} = \mathfrak{sl}_2(\mathbb{C})$   $e, h, f$  as usual.

Let exponentiate  $t e$ ,  $t f$  in natural representation, any  $t \in \mathbb{C}$ .

$$\exp(t e) = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 0 & t \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$$

$$\exp(t f) = \begin{pmatrix} 1 & 0 \\ t & 1 \end{pmatrix}$$

$$x(t) \in \mathrm{SL}_2(\mathbb{C})$$

$$x(t)x(t') = x(t+t')$$

$$\text{So: } x: \mathbb{G}_a \rightarrow \mathrm{SL}_2(\mathbb{C})$$

$$y: \mathbb{G}_a \rightarrow \mathrm{SL}_2(\mathbb{C}) \longleftarrow \text{a morphism of alg. gps.}$$

Images of  $x$  &  $y$ : "1-parameter subgroups" or "root groups"

$$\text{Now observe } \mathrm{SL}_2(\mathbb{C}) = \langle \underbrace{x(t)}_X, \underbrace{y(t)}_Y \mid t \in \mathbb{C} \rangle.$$

$$L(x) = \langle e \rangle \quad L(y) = \langle f \rangle$$

HW1-Q2: Given a family  $x_i: \mathbb{G}_a \rightarrow GL_n(\mathbb{C})$  ( $i \in I$ )

of morphisms of algebraic groups, the subgroup generated by their images is closed & connected, hence, a connected alg. gp. itself.

Take  $t \in \mathbb{C}^\times$ . Let

$$G(t) = x(t) y(-t^{-1}) x(t)$$

$$\begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -t^{-1} & 1 \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & t \\ -t^{-1} & 1 \end{pmatrix} \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix} = \underbrace{\begin{pmatrix} 0 & t \\ -t^{-1} & 0 \end{pmatrix}}_{G(t) \in SL_2(\mathbb{C})}$$

I'll write

$$G = G(1)$$

$$\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \in SL_2(\mathbb{C})$$

Define

$$\gamma(t) = G(t) G(-1)$$

$$\begin{pmatrix} 0 & t \\ -t^{-1} & 0 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} t & 0 \\ 0 & t^{-1} \end{pmatrix} \in SL_2(\mathbb{C})$$

$\gamma: \mathbb{G}_m \rightarrow SL_2(\mathbb{C})$  another morphism of algebraic groups

Given a 1-psg  $T = \{ \gamma(t) \mid t \in \mathbb{C}^\times \}$  1-D torus  $L(T) = \mathbb{Z} = \langle 1 \rangle$

Example 2  $\mathfrak{g} = \mathfrak{sl}_2(\mathbb{C})$  in representation  $\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$

$$\exp(\text{ad } te) = \begin{pmatrix} 1 & -2t & -t^2 \\ 0 & 1 & t \\ 0 & 0 & 1 \end{pmatrix} \in \text{PSL}_2(\mathbb{C})$$

$\text{Ad}(x(t))$

$$\text{ad } te = \begin{pmatrix} e & h & f \\ 0 & -2t & 0 \\ 0 & 0 & t \\ 0 & 0 & 0 \end{pmatrix}$$

$$\exp(\text{ad } tf) = \begin{pmatrix} 1 & 0 & 0 \\ -t & 1 & 0 \\ -t^2 & 2t & 1 \end{pmatrix} \in \text{PSL}_2(\mathbb{C})$$

$\text{Ad}(y(t))$

$$\text{ad } tf = \begin{pmatrix} 0 & 0 & 0 \\ -t & 0 & 0 \\ 0 & 2t & 0 \end{pmatrix}$$

$$\text{Ad}(g(t)) = \begin{pmatrix} 0 & 0 & -t^2 \\ 0 & -1 & 0 \\ -t^{-2} & 0 & 0 \end{pmatrix} \in \text{PSL}_2(\mathbb{C})$$

$$\text{Ad}(g) = \begin{pmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ -1 & 0 & 0 \end{pmatrix}$$

$$h \mapsto -h$$

$$\text{Ad}(\gamma(t)) = \begin{pmatrix} t^2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & t^{-2} \end{pmatrix} \in \text{PSL}_2(\mathbb{C})$$

$$\text{Ad}(\gamma(t))(e) = t^2 e$$

$$(\text{ad } h)(e) = 2e$$

$\uparrow$   
 $\text{Ad } T$

$\uparrow$   
 $\text{ad } t$

Example 3 Cartan matrix  $C = ((\alpha_i, \alpha_j^\vee))_{i,j=1,\dots,l}$

$\mathfrak{g} = \mathfrak{g}(C)$  as given by Serre presentation.

$$S_i = \langle e_i, h_i, f_i \rangle \quad \theta_i = (\exp \text{ad } e_i)(\exp \text{ad } (-f_i))(\exp \text{ad } e_i) \in \text{Aut}(\mathfrak{g})$$

On  $h_i$ ,  $\theta_i(h_i) = -h_i$

On  $\ker(\alpha_i) \subset \mathfrak{h} = \langle h_1, \dots, h_l \rangle$ ,  $\theta_i$  is the identity  
(codim-1 subspace)

$\Rightarrow \theta_i$  acts on  $\mathfrak{h}$  sending  $h_i \mapsto -h_i$ , fixing  $\ker(\alpha_i)$

$$\Rightarrow \lambda(\theta_i^{-1}(h)) = s_i(\lambda)(h) \quad \forall \lambda \in \mathfrak{h}^*$$

$\lambda - (\lambda, \alpha_i^\vee) \alpha_i$

step missing in proof of Serre in L9-3

$$\Rightarrow \theta_i(\mathfrak{g}_\lambda) = \mathfrak{g}_{s_i(\lambda)}$$

$$[h, \theta_i(x)] = \theta_i[\theta_i^{-1}(h), x] = \lambda(\theta_i^{-1}(h)) \theta_i(x) = (s_i(\lambda))(h) (\theta_i(x))$$

Example 4 Still  $\mathfrak{g} = \mathfrak{sl}(n, \mathbb{C})$  f.d. semisimple Lie algebra.

Let  $V$  any f.d.  $\mathfrak{g}$ -module.  $\rho: \mathfrak{g} \rightarrow \mathfrak{gl}(V)$

Let  $s_i = \exp \rho(e_i) \exp \rho(-f_i) \exp \rho(e_i)$

Argument above shows ...  $s_i(V_\lambda) = V_{s_i(\lambda)}$   
↙ with simple reflection  $s_i$  in  $\mathcal{W}$

$$\implies \dim V_\lambda = \dim V_{w(\lambda)} \\ \forall w \in \mathcal{W}$$

Weight space dimensions are constant on  $\mathcal{W}$ -orbits