

Tangent space

Let X be an affine variety, $x \in X \rightsquigarrow T_x(X)$ tangent space to X at x .

Assume to start with given coordinates

$$x: X \subseteq \mathbb{A}^n \xleftarrow{\text{closed embedding}} \frac{\mathbb{k}[T_1, \dots, T_n]}{I} = \mathbb{k}[X]$$

$$I = I(X) = \langle f_1, \dots, f_s \rangle$$

Take a line L in \mathbb{A}^n passing through x

" $x + tv$ for $t \in \mathbb{k}$ and $v = (v_1, \dots, v_n) \in \mathbb{k}^n$

Then $L \cap X$ is all $x + tv$ such that $f_i(x + tv) = 0 \quad (i=1, \dots, s)$

$\leftarrow t=0$ is a solution

Call L a tangent line to X at x if $t=0$ is a multiple root of these equations.

Call v a tangent vector

Then $T_x(X) = \{ \text{all tangent vectors } v \in \mathbb{k}^n \}$

$$\frac{\partial}{\partial T_i} : \mathbb{K}[T_1, \dots, T_n] \rightarrow \mathbb{K}[T_1, \dots, T_n]$$

Taylor expansion of $f_i : \mathbb{K}^n \rightarrow \mathbb{K}$ at x :

$$f_i(x + t v) = t \sum_{j=1}^n \frac{\partial f_i}{\partial T_j}(x) v_j + t^2 \square + \dots$$

Saying " $t=0$ is a multiple root" means the linear term is zero for all i .

$$\text{So: } v \in T_x(X) \iff$$

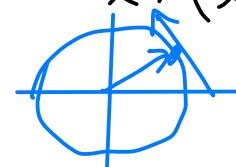
$$\boxed{\sum_{j=1}^n \frac{\partial f_i}{\partial T_j}(x) v_j = 0} \quad (i=1, \dots, s)$$

provisional definition!

$$T_x(X) = \ker \left(\frac{\partial f_i}{\partial T_j}(x) \right)_{\substack{i=1, \dots, s \\ j=1, \dots, n}} \leq \mathbb{K}^n \text{ s } \times n \text{ matrix}$$

$$\textcircled{(1)} \quad X = \mathbb{A}^n, s=0 \quad | \quad (2) \quad X = V(T_1^2 + T_2^2 - 1) \subseteq \mathbb{A}^2 \quad \ker (2x_1, 2x_2)$$

$$T_x(X) = \mathbb{K}^n$$



$$p=2? \quad T_1^2 + T_2^2 - 1 = (T_1 + T_2)^2 \text{ wrong!}$$

Def $D : |k[X]| \rightarrow |k[X]|$ linear map is a derivation if

Leibniz holds: $D(fg) = D(f)g + f D(g)$ $\xrightarrow{D(1) = 0}$

Let $\text{Der}(|k[X]|, |k[X]|)$ be vector space of all derivations



$$\cong \text{End}_{\mathbb{K}}(|k[X]|)$$

Not an associative subalgebra

It is a Lie subalgebra!!!

assoc. algebra ... so a Lie algebra via $[::]$
then its called $\text{ogl}(|k[X]|)$

(Commutator $[D_1, D_2]$ of two
derivations is a derivation.)

\Downarrow If $D : |k[X]| \rightarrow |k[X]|$ is a derivation then

$$\boxed{\overline{D} = \underset{x}{\text{ev}} \circ D}$$
 is a point derivation

For $x \in X$, let $|k_x| = |k[X]| / M_x$ $\xrightarrow{M_x = \ker \text{ev}_x}$

$$\text{let } \text{Der}(|k[X]|, |k_x|) = \left\{ \overline{D} : |k[X]| \rightarrow |k_x| \mid \overline{D}(fg) = \overline{D}(f)g(x) + f(x)\overline{D}(g) \right\}$$



vector space of point derivations for point x

$\text{Der}(\mathbb{k}[T_1, \dots, T_n], \mathbb{k}_x)$?

$$\begin{array}{ccc}
 \mathbb{k}^n & \xrightarrow[\text{(+) }]{\sim} & \text{Der}(\mathbb{k}[T_1, \dots, T_n], \mathbb{k}_x) \\
 v = (v_1, \dots, v_n) & & \\
 v \mapsto \bar{D}_v & &
 \end{array}$$

$\boxed{ev_x \circ \sum_{j=1}^n v_j \frac{\partial}{\partial T_j}}$

call this \bar{D}_v

This is an isomorphism

Proof: Any $\bar{D} \in \text{Der}(\mathbb{k}[T_1, \dots, T_n], \mathbb{k}_x)$ equals \bar{D}_v where $v_j := \bar{D}(T_j)$.

Now see $\bar{D} \mapsto v$ for v defined in this way is 2-sided inverse

$$\begin{aligned}
 \text{Earlier we showed } T_x(X) &= \left\{ v \in \mathbb{k}^n \mid \bar{D}_v f_i = 0 \quad i = 1, \dots, n \right\} \\
 &= \left\{ v \in \mathbb{k}^n \mid \bar{D}_v I(X) = 0 \right\} \\
 \text{Our } T_x(X) \text{ (up to iso...)} &\stackrel{\cong}{\downarrow} (\text{+}) \\
 \boxed{\text{Der}(\mathbb{k}[X], \mathbb{k}_x)} &\cong \left\{ \bar{D} \in \text{Der}(\mathbb{k}[T_1, \dots, T_n], \mathbb{k}_x) \mid \bar{D} I(X) = 0 \right\}
 \end{aligned}$$

Def.: X affine, $x \in X$. The target space to X at x is

the vector space

$$T_x(X) := \text{Der}(\mathbb{k}[X], \mathbb{k}_x)$$

(point derivations for the point x)

Coordinate free !! Functional --

morphism of affine varieties, get linear map

$$\begin{matrix} \varphi: & X & \rightarrow & Y \\ & x & \mapsto & y \\ & & x & \mapsto y \end{matrix}$$

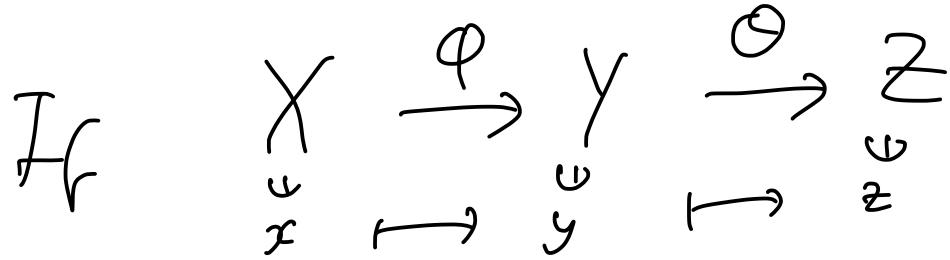
$$d\varphi_x: T_x(X) \rightarrow T_x(Y) \quad \text{differential of } \varphi \text{ at } x$$

$$\bar{D} \mapsto (d\varphi_x)(\bar{D}) \quad \text{where} \quad (d\varphi_x)(\bar{D})(f) := \bar{D}(\varphi^* f)$$

$$\mathbb{k}[Y] \quad \mathbb{k}[X]$$

Why is this a point derivation $\mathbb{k}[Y] \rightarrow \mathbb{k}_y$?

$$\begin{aligned} \bar{D}(\varphi^*(fg)) &= \bar{D}(\varphi^*_f \cdot \varphi^*_g) = \bar{D}(\varphi^*_f)(\varphi^*_g)(x) + (\varphi^*_f)(x) \bar{D}(\varphi^*_g) \\ &= \bar{D}(\varphi^*_f)g(y) + f(y) \bar{D}(\varphi^*_g) \quad \checkmark \end{aligned}$$



$$d(\theta \circ \phi)_x : T_x(X) \rightarrow T_z(Z)$$

||

$$d\theta_y \circ d\phi_x$$

"chain rule"

$$(\text{as } (\theta \circ \phi)^* = \theta^* \circ \phi^*).$$

Passing to target space / differential is a functor from pointed aff. varieties to f.d. vector spaces.

We just saw
exactly this for

$$X \hookrightarrow \mathbb{A}^n$$

Other observations

$$T_{(x,y)}(X \times X) = T_x(X) \oplus T_y(Y)$$

- $T_{(x,y)}(X \times X) = T_x(X) \oplus T_y(Y)$
- If $\phi: \overset{\cong}{Z} \hookrightarrow X$ is a closed embedding then $d\phi_z: T_z(Z) \rightarrow T_z(X)$ is isomorphic. $T_z(Z) \cong \{ \bar{D} \in T_z(X) \mid \bar{D}|_Z = 0 \}$

- $f \in k[X]$, $x \in D(f)$ i.e. $f(x) \neq 0$
- $i: D(f) \hookrightarrow X$. Its differential is an isomorphism
- $d_i_x: T_{x,C}(D(f)) \xrightarrow{\sim} T_{x,C}(X)$ "tangent space only sees a neighborhood of x "

$$[k[D(f)]] = [k[X]]_f$$

Have $\text{Der}([k[X]_f], k_x) \rightarrow \text{Der}([k[X]], k_x)$

"restriction along" $i^*: [k[X]] \rightarrow [k[X]]_f$

We need to show any $\bar{D} \in \text{Der}([k[X]], k_x)$ "lifts" to $[k[X]]_f \rightarrow k$

Issue is to define $\bar{D}\left(\frac{g}{f}\right) = \frac{\bar{D}(g)f(x) - g(x)\bar{D}(f)}{f(x)^2}$...

$\bar{D}\left(\frac{g}{f}\right) \dots$ no charé

makes sense as $f(x) \neq 0$

④ $T_e(GL_n(\mathbb{K})) = T_e(M_n(\mathbb{K})) \stackrel{\exists}{=} M_n(\mathbb{K})$

$\text{ev}_e \circ \frac{\partial}{\partial T_{ij}} \in \text{Der}(\mathbb{K}[M_n(\mathbb{K})], \mathbb{K}_e) \longleftrightarrow$

$\begin{matrix} \uparrow \\ e_{ij} \text{ ij-matrix} \\ \text{linear basis} \end{matrix}$

$$\mathbb{K}[M_n(\mathbb{K})] = \mathbb{K}[T_{ij} \mid 1 \leq i, j \leq n]$$

④ $T_e(SL_n(\mathbb{K})) = \left\{ \cancel{x} \in M_n(\mathbb{K}) \mid \overline{D}_{x'A} (\det - 1) = 0 \right\}$

$A = (a_{ij})_{1 \leq i, j \leq n} = \sum a_{ij} e_{ij} \quad \{A \in M_n(\mathbb{K}) \mid \text{tr } A = 0\}$

$\sqrt{(\det - 1)}$

\uparrow

all matrices $A \in M_n(\mathbb{K})$ s.t. $\sum_{i,j=1}^n a_{ij} \left[\frac{\partial}{\partial T_{ij}} (\det - 1) \right](e) = 0$

SL₂? $\sum a_{ij} \frac{\partial}{\partial T_{ij}} (T_{11}T_{22} - T_{12}T_{21} - 1)(e) = 0$

It's 2x2 matrices
of trace zero

$$a_{11} T_{22}(e) + a_{22} T_{11}(e) = \frac{a_{11} + a_{22}}{\text{tr}(A)}$$