

Problem Assignment # 2

01/15/2025
due 01/22/2025**0.2.4. Functional derivative** (3 pts)

Let $F[\varphi]$ be a functional of a real-valued function $\varphi(x)$. For simplicity, let $x \in \mathbb{R}$; the generalization to more than one dimension is straightforward. We can (sloppily) define the *functional derivative* of F as

$$\frac{\delta F}{\delta \varphi(x)} := \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \left(F[\varphi(y) + \epsilon \delta(y-x)] - F[\varphi(y)] \right)$$

a) Calculate $\delta F / \delta \varphi(x)$ for the following functionals:

i) $F = \int dx \varphi(x)$

ii) $F = \int dx \varphi^2(x)$

iii) $F = \int dx f(\varphi(x)) g(\varphi(x))$ where f and g are given functions

iv) $F = \int dx (\varphi'(x))^2$ where $\varphi'(x) = d\varphi/dx$

hint: Integrate by parts and assume that the boundary terms vanish.

v) $F = \int dx V(\varphi'(x))$ where V is some given function.

remark: Blindly ignore terms that formally vanish as $\epsilon \rightarrow 0$ unless you want to find out why the above definition is very problematic. It does work for operational purposes, though.

b) Consider a Lagrangian density $\mathcal{L}(\varphi(x), \partial_\mu \varphi(x))$ and an action $S = \int d^4x \mathcal{L}$. Show that extremizing S by requiring $\delta S / \delta \varphi(x) \equiv 0$ with the above definition of the functional derivative leads to the Euler-Lagrange equations

$$\partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} = \frac{\partial \mathcal{L}}{\partial \varphi}$$

0.2.5. Massive scalar field (2 pts)

Consider the Lagrangian density for a massive scalar field from the example in ch. 0 §2.5.

a) Generalize this Lagrangian density to a complex field $\phi(x) \in \mathbb{C}$:

$$\mathcal{L} = \frac{1}{2} (\partial_\mu \phi(x)) (\partial^\mu \phi^*(x)) - \frac{m^2}{2} |\phi(x)|^2$$

with ϕ^* the complex conjugate of ϕ . What are the Euler-Lagrange equations now?

b) Consider a local gauge transformation, $\phi(x) \rightarrow \phi(x) e^{i\Lambda(x)}$, with $\Lambda(x)$ a real field that characterizes the transformation. Is the Lagrangian from part b) invariant under such a transformation?

... /over

0.3.1. Particle in homogeneous \mathbf{E} and \mathbf{B} fields (6 pts)

Consider a point particle (mass m , charge e) in homogeneous fields $\mathbf{B} = (0, 0, B)$ and $\mathbf{E} = (0, E_y, E_z)$. Treat the motion of the particle nonrelativistically.

a) Show that the motion in z -direction decouples from the motion in the x - y plane, and find $z(t)$.

b) Consider $\xi := x + iy$. Find the equation of motion for ξ , and its most general solution.

hint: Define the *cyclotron frequency* $\omega = eB/mc$, and remember how to solve inhomogeneous ODEs.

c) Show that the time-averaged velocity perpendicular to the plane defined by \mathbf{B} and \mathbf{E} is given by the *drift velocity*

$$\langle \mathbf{v} \rangle = c \mathbf{E} \times \mathbf{B} / B^2$$

Show that $E_y/B \ll 1$ is necessary and sufficient for the non relativistic approximation to be valid.

d) Show that the path projected onto the x - y plane can have three qualitatively different shapes, and plot a representative example for each.

0.3.2. Harmonic oscillator coupled to a magnetic field (4 pts)

Consider a charged 3-d classical harmonic oscillator (oscillator frequency ω_0 , charge e). Put the oscillator in a homogeneous time-independent magnetic field $\mathbf{B} = (0, 0, B)$. Show that the motion remains oscillatory, and find the oscillation frequencies in the directions parallel and perpendicular, respectively, to \mathbf{B} .

0.2.4. Functional derivative

Let $F[\varphi]$ be a functional of a real-valued function $\varphi(x)$. For simplicity, let $x \in \mathbb{R}$; the generalization to more than one dimension is straightforward. We can (sloppily) define the *functional derivative* of F as

$$\frac{\delta F}{\delta \varphi(x)} := \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \left(F[\varphi(y) + \epsilon \delta(y-x)] - F[\varphi(y)] \right)$$

a) Calculate $\delta F/\delta \varphi(x)$ for the following functionals:

i) $F = \int dx \varphi(x)$

ii) $F = \int dx \varphi^2(x)$

iii) $F = \int dx f(\varphi(x)) g(\varphi(x))$ where f and g are given functions

iv) $F = \int dx (\varphi'(x))^2$ where $\varphi'(x) = d\varphi/dx$

hint: Integrate by parts and assume that the boundary terms vanish.

v) $F = \int dx V(\varphi'(x))$ where V is some given function.

remark: Blindly ignore terms that formally vanish as $\epsilon \rightarrow 0$ unless you want to find out why the above definition is very problematic. It does work for operational purposes, though.

b) Consider a Lagrangian density' $\mathcal{L}(\varphi(x), \partial_\mu \varphi(x))$ and an action' $S = \int d^4x \mathcal{L}$. Show that extremizing S by requiring $\delta S/\delta \varphi(x) \equiv 0$ with the above definition of the functional derivative leads to the Euler-Lagrange equations

$$\partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} = \frac{\partial \mathcal{L}}{\partial \varphi}$$

(3 points)

Solution

a) i) $\frac{\delta F}{\delta \varphi(x)} = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy [\varphi(y) + \epsilon \delta(y-x) - \varphi(y)] = \int dy \delta(y-x) = 1$

ii) $\frac{\delta F}{\delta \varphi(x)} = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy [(\varphi(y) + \epsilon \delta(y-x))^2 - \varphi(y)^2] = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy [2\epsilon \varphi(y) \delta(y-x) + O(\epsilon^2)] = 2\varphi(x)$

iii) $\frac{\delta F}{\delta \varphi(x)} = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy [f(\varphi(y) + \epsilon \delta(y-x))][g(\varphi(y) + \epsilon \delta(y-x)) - f(\varphi(y))g(\varphi(y))] = f'(\varphi(x))g(\varphi(x)) + f(\varphi(x))g'(\varphi(x))$ 1pt

iv) $\frac{\delta F}{\delta \varphi(x)} = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy \left[(\varphi'(y) + \epsilon \frac{d}{dy} \delta(y-x))^2 - (\varphi'(y))^2 \right] = 2 \int dy \varphi'(y) \frac{d}{dy} \delta(y-x) = -2\varphi''(x)$

v) $\frac{\delta F}{\delta \varphi(x)} = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy \left[V\left(\varphi'(y) + \epsilon \frac{d}{dy} \delta(y-x)\right) - V(\varphi'(y)) \right] = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int dy \left[\epsilon V'(\varphi'(y)) \frac{d}{dy} \delta(y-x) + O(\epsilon^2) \right] = -V''(\varphi'(x)) \varphi''(x)$ 1pt

b) $0 = \frac{\delta}{\delta \varphi(x)} \int d^4y \mathcal{L}(\varphi(y), \partial_\mu \varphi(y)) = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int d^4y [\mathcal{L}(\varphi(y) + \epsilon \delta(y-x), \partial_\mu \varphi(y) + \epsilon \partial_\mu \delta(y-x)) - \mathcal{L}(\varphi(y), \partial_\mu \varphi(y))] = \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int d^4y \left[\epsilon \delta(y-x) \frac{\partial \mathcal{L}}{\partial \varphi(y)} + \epsilon (\partial_\mu \delta(y-x)) \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi(y))} + O(\epsilon^2) \right] = \frac{\partial \mathcal{L}}{\partial \varphi(x)} - \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi(x))}$ EL ✓ 1pt

0.2.5.7 a) Treat $\phi(x)$ and $\phi^*(x)$ as independent fields

Minimizing with respect to ϕ^* yields

$$(\partial_\mu \partial^\mu + m^2) \phi(x) = 0$$

and minimizing with respect to ϕ just yields the c.c.

$$(\partial_\mu \partial^\mu + m^2) \phi^*(x) = 0$$

①

b) Under $\phi(x) \rightarrow \phi(x) e^{i\Delta(x)}$ we have

$$|\phi(x)|^2 \rightarrow |\phi(x)|^2$$

and

$$\partial_\mu \phi(x) \rightarrow (\partial_\mu \phi(x)) e^{i\Delta(x)} + i(\partial_\mu \Delta(x)) \phi(x) e^{i\Delta(x)}$$

$$\partial^\mu \phi^*(x) \rightarrow (\partial^\mu \phi^*(x)) e^{-i\Delta(x)} - i(\partial^\mu \Delta(x)) \phi^*(x) e^{-i\Delta(x)}$$

$$\begin{aligned} \rightarrow \partial_\mu \phi(x) \partial^\mu \phi^*(x) &\rightarrow \partial_\mu \phi(x) \partial^\mu \phi^*(x) - i(\partial^\mu \Delta(x)) (\partial_\mu \phi(x)) \phi^*(x) \\ &\quad + i(\partial_\mu \Delta(x)) (\partial^\mu \phi^*(x)) \phi(x) \\ &\quad + (\partial_\mu \Delta(x)) (\partial^\mu \Delta(x)) |\phi(x)|^2 \end{aligned}$$

$$+ \partial_\mu \phi \partial^\mu \phi^*$$

①

→ The Lagrangian is not invariant

0.3.1.) a) Eq. of motion:

$$m\vec{\ddot{v}} = e\vec{E} + \frac{e}{c}\vec{v}\times\vec{D}$$

$$\text{with } \vec{D} = (0, 0, D) \text{ and } \vec{E} = (0, E_y, E_z)$$

$$\rightarrow \begin{array}{|l} m\ddot{x} = \frac{e}{c}yD & (1) \\ m\ddot{y} = eE_y - \frac{e}{c}x\dot{D} & (2) \\ m\ddot{z} = eE_z & (3) \end{array}$$

$$(3) \rightarrow \underline{\underline{z(t) = z_0 + v_z^0 t + \frac{eE_z}{2m} t^2}}$$

b) Define $\underline{\underline{\zeta := x + iy}}$

$$(1) + i \cdot (2) \rightarrow m\dot{\zeta} = ieE_y - i\frac{eD}{c}\zeta$$

Define $\omega := \frac{eD}{mc}$ cyclotron frequency

$$\rightarrow \boxed{\dot{\zeta} + i\omega\zeta = i\frac{e}{m}E_y} \quad (*)$$

Special solution of inhomogeneous eq: $\dot{\zeta} = \frac{eE_y}{m\omega}$ General solution of homogeneous eq: $\dot{\zeta} = a e^{-i\omega t} \quad (a \in \mathbb{C})$

$$\rightarrow \underline{\underline{\zeta(t) = a e^{-i\omega t} + eE_y/m\omega}}$$
 is the most general solution of (*).
c) With $a = b e^{i\alpha}$, $b, \alpha \in \mathbb{R}$

$$\rightarrow \zeta = b e^{-i(\omega - \alpha)t} + eE_y/m\omega$$

$$\rightarrow \alpha \text{ just shifts the zero of time } \rightarrow \underline{\underline{\alpha = 0 \text{ w.l.o.g.}}}$$

$$\rightarrow \dot{x} + i\dot{y} = b\omega e^{i\omega t} - ib\omega e^{-i\omega t} + eE_y/m\omega$$

$$\rightarrow \begin{cases} \dot{x} = b\omega e^{i\omega t} + eE_y/m\omega \\ \dot{y} = -b\omega e^{-i\omega t} \end{cases} \quad (**)$$

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$$\rightarrow \langle \dot{y} \rangle = 0, \quad \langle \dot{x} \rangle = eE_y/m\omega = \frac{cE_y/\omega}{\omega^2} \quad \text{time-averaged velocity}$$

$$= \frac{cE_y\omega}{\omega^2} = \frac{c(\vec{E} \times \vec{\omega})_x}{\omega^2}$$

i general:

$$\langle \vec{v} \rangle = \frac{c}{\omega^2} \vec{E} \times \vec{\omega} \quad \text{drift velocity}$$

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$$\text{condition for } v \ll c: \quad \frac{E_y/\omega}{\omega} \ll 1$$

necessary condition sufficient
condition for non-relativistic approximation

d) Given $x(t=0) = 0 = y(t=0)$ w.l.o.

$$(**) \rightarrow \begin{cases} x(t) = \frac{b}{\omega} \omega t + \frac{cE_y}{\omega^2} t \\ y(t) = \frac{b}{\omega} (\omega t - 1) \end{cases}$$

\rightarrow The path is a trochoid.

To visualize it, put $\omega = 1$ and define $C = cE_y/\omega^2$.

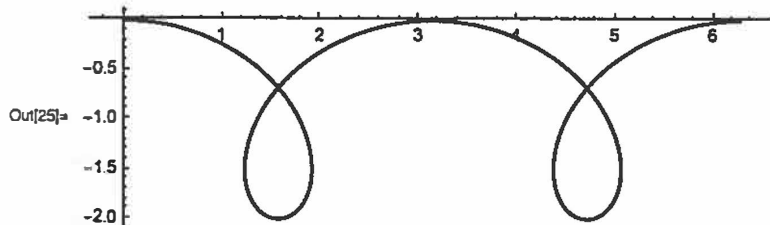
$$\rightarrow \begin{cases} x(t) = b \omega t + Ct \\ y(t) = b (\omega t - 1) \end{cases}$$

This is the projection of the path onto the x-y plane

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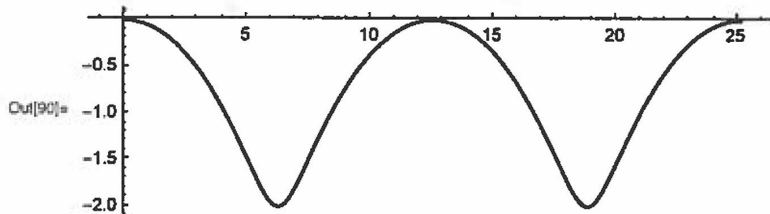
For $C < b$ the trochoid has loops :

```
In[21]= b = 1;
c = 0.5;
x[t_] := b Sin[t] + c t
y[t_] := b (Cos[t] - 1)
ParametricPlot[{x[t], y[t]}, {t, 0, 4 Pi}]
```



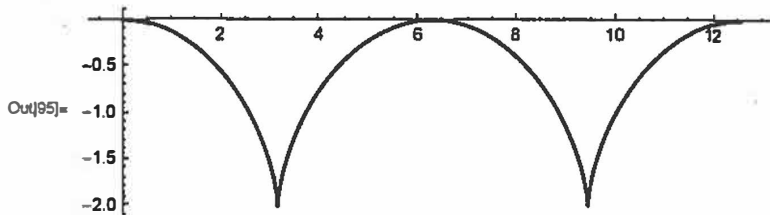
For $C > b$ it does not :

```
In[86]= b = 1;
c = 2;
x[t_] := b Sin[t] + c t
y[t_] := b (Cos[t] - 1)
ParametricPlot[{x[t], y[t]}, {t, 0, 4 Pi}, AspectRatio -> 0.3]
```



And for $C = b$ it degenerates into a cycloid :

```
In[91]= b = 1;
c = 1;
x[t_] := b Sin[t] + c t
y[t_] := b (Cos[t] - 1)
ParametricPlot[{x[t], y[t]}, {t, 0, 4 Pi}, AspectRatio -> 0.3]
```



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0.3.2.) In addition to the restoring force $-m\omega_0^2 x$, the particle is subject to a Lorentz force

$$\frac{e}{c} \vec{v} \times \vec{B} = \frac{e}{c} (\dot{y} B, -\dot{x} B, 0)$$

→ The eqs of motion are

$$\ddot{x} + \omega_0^2 x = R \dot{y} \quad (1)$$

$$\ddot{y} + \omega_0^2 y = -R \dot{x} \quad (2)$$

$$\ddot{z} + \omega_0^2 z = 0 \quad (3)$$

(1) with $R := eB/mc$ the cyclotron frequency.

(3) → For oscillations in the z -direction, the frequency

$\omega = \omega_0$ is unchanged

Define $f := x + iy$ and consider

$$(1) + i \cdot (2) \rightarrow \boxed{\ddot{f} + \omega_0^2 f = -iR \dot{f}}$$

ansatz: $f(t) = f_0 e^{i\omega t}$

$$\rightarrow -\omega^2 f_0 + \omega_0^2 f_0 =$$

$$\omega^2 + R\omega - \omega_0^2 = 0$$

$$\rightarrow \omega = \frac{1}{2} (-R \pm \sqrt{R^2 + 4\omega_0^2}) = \pm \sqrt{\omega_0^2 + R^2/4} - R/2$$

→ The motion in the x - y plane is oscillatory, and eigenfrequencies are

$$\omega_{\pm} = \sqrt{\omega_0^2 + R^2/4} \pm R/2$$