Dancing on Water: The Choreography of Sulfur Dioxide Adsorption to Aqueous Surfaces

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1. INTRODUCTION

The doorway to the uptake of a gas by an aqueous solution is the water surface. Although we know much about the behavior of a gas on either side of that entrance, far less is known about how that surface acts to attract, facilitate, or thwart the transit of a molecule between the two bulk phases. What is not commonly known is how an atmospheric gas such as SO₂ and molecules at the water surface can overcome the barrier created by strong water–water surface bonding interactions. What this interplay looks like, the distances from the water surface at which these attractive interactions begin, and how they influence the orientational nature of both SO₂ and surface water molecules is the focus of this computational study. The results fill a void in the information about this system existing from previous experimental studies by providing information about the dimensional nature of the gas–surface interactions, and the details of how the two species twist and turn orientationally with increased surface interactions. Classical molecular dynamics have been employed in both equilibrium and steered molecular dynamics (SMD) simulations for SO₂ at a neat-water surface and at a surface with high interfacial SO₂ concentrations. The results provide new molecular insights for understanding the interaction of this prevalent gas on aerosols and other aqueous surfaces in the environment.

ABSTRACT: One might expect the high surface tension of water to be a barrier to absorption of a gas into the liquid phase, but we know that gaseous adsorption onto and subsequent absorption into a water surface is a common phenomenon on this planet. What is not commonly known is how an atmospheric gas such as SO₂ and molecules at the water surface can overcome the barrier created by strong water–water surface bonding interactions. What this interplay looks like, the distances from the water surface at which these attractive interactions begin, and how they influence the orientational nature of both SO₂ and surface water molecules is the focus of this computational study. The results fill a void in the information about this system existing from previous experimental studies by providing information about the dimensional nature of the gas–surface interactions, and the details of how the two species twist and turn orientationally with increased surface interactions. Classical molecular dynamics have been employed in both equilibrium and steered molecular dynamics (SMD) simulations for SO₂ at a neat-water surface and at a surface with high interfacial SO₂ concentrations. The results provide new molecular insights for understanding the interaction of this prevalent gas on aerosols and other aqueous surfaces in the environment.

1. INTRODUCTION

The doorway to the uptake of a gas by an aqueous solution is the water surface. Although we know much about the behavior of a gas on either side of that entrance, far less is known about how that surface acts to attract, facilitate, or thwart the transit of a molecule between the two bulk phases. What is the interplay between the gas and surface water molecules, and when does one begin to influence the behavior of the other? What species form during gas adsorption onto liquid surfaces, and what are the intermediary steps? Is molecular orientation of either the gas or surface molecules a factor in the adsorption process? Are specific gas or liquid molecular orientations necessary for gaseous adsorption? Experimental studies to address such questions are valuable but do not provide the full resolution necessary to determine the geometries of adsorbing gases, or to determine the orientations of the molecules at the liquid surface near the adsorption site. This type of information can be determined computationally, and when coupled to the experimental studies can provide a more comprehensive picture of the gas–liquid surface adsorption process.

An important gas for developing a picture of gaseous adsorption and entry into a water surface is sulfur dioxide.1–11 SO₂ enters the environment as an important industrial product, and also naturally through terrestrial processes. Atmospheric dust particles and gases have been implicated in the oxidation of SO₂, and act as reaction surfaces for chemical mechanisms that are still poorly understood.12–16 SO₂ acts as a major component of atmospheric pollution, and is a precursor to acid rain formation, and cloud nucleation. Its high solubility in water makes SO₂ an integral compound in many aqueous atmospheric reactions, as well. Obtaining a more complete picture of the SO₂ adsorption process is important for understanding gaseous adsorption of this environmentally important gas on water and aerosol surfaces as well as being a model system for understanding the more general nature of gases at aqueous interfaces.

In this work we provide a molecular picture of SO₂ adsorption on a water surface. This study demonstrates the strong orientational effect of surface water molecules on the adsorbing gas during the approach and entry into the surface region at both high and low SO₂ surface concentrations. These computational studies complement and significantly expand the picture developed in our recent experimental vibrational sum frequency spectroscopy (VSFS) studies of SO₂ adsorption of aqueous solutions of various compositions and temperatures,17,18 and the subsequent studies using both classical and ab initio simulations. These experimental studies showed that an SO₂ surface hydrate complex forms when an aqueous surface is exposed to SO₂ gas. The computational study by Baer et al.19 then made a series of predictions of the specific nature of the hydrated complex through classical and ab initio simulations. That work developed a detailed picture of the nature of the SO₂ surface complex with water, and related it to the surface water OH vibrational IR spectra. The most recent experimental studies have shown that, whereas the binding of gaseous SO₂ to a water...
surface is greatly enhanced at cold temperatures, the reversibility of the adsorption process remains. Complementary experiments showed that low pH aqueous environments inhibit the bulk reactions of SO$_2$ but do not affect the surface binding or its reversibility. What is apparent in the VSF spectra obtained in all of these experiments is the tendency of water to reorient upon surface bonding, with the effect becoming more pronounced at high SO$_3$ surface concentrations. Since the SO$_2$ molecule was not specifically probed, conclusions on how SO$_2$ bonding contributes to reorienting surface water molecules and the orientation of SO$_3$ itself upon approach and surface bonding could only be inferred.

To fill this void, the computational studies described herein provide a detailed picture of the orientation of both SO$_2$ and surface water molecules during the adsorption process. The depth profiling studies that examine the orientation of both species during the approach and entry of the gas into the interfacial region are obtained using equilibrium and steered (SMD) classical molecular dynamics simulations. The latter approach involves steering a gas molecule into the aqueous phase, and characterizing its molecular orientation as it transits through the interfacial region. This unique approach enables new insights into the behaviors of gas molecules as they move near liquid water. We also simulate how SO$_2$ adsorption occurs on a water surface saturated with adsorbed SO$_2$, analogous to the conditions of the single-SO$_2$ neat-water system was then evolved for 2 ns to produce an equilibrated starting configuration. Because of the extremely low concentration of SO$_3$ in the neat-water system, the surface waters behave similarly to a true neat-water air—liquid interface. The neat-water system orientational results shown later in this work reproduce well the results of our previous orientational studies of surface water behavior. The saturated system had 22 SO$_2$ molecules introduced to the water slab bulk in order to saturate it to a level coinciding with the Henry’s law constant for SO$_2$ in water (k$_{H}$ = 1.4 mol/kg·bar). Additionally, 50 SO$_2$ molecules were introduced into the gas phase outside of the saturated water slab to simulate an added SO$_2$ gas pressure. The additional gas in the vapor phase was added over the course of several nanoseconds to keep a constant 1 atm of SO$_2$ pressure above the water surface as SO$_2$ gas molecules adsorbed to the surface. The saturated system with both bulk and gaseous SO$_2$ was then evolved for 2 ns to produce a starting configuration for further saturated simulations.

2. COMPUTATIONAL APPROACH

Molecular dynamics simulations were performed using the Amber 11 software suite. Polarizable models for the H$_2$O and SO$_2$ molecules were used in the simulations, and have been used previously in studies on interfacial systems because they are known to more accurately reproduce interfacial structure and free energy profiles. The H$_2$O model used is the POL3 model (also discussed in the Supporting Information), and for SO$_2$ we used the model of Baer et al., which places a single polarizable center on the sulfur atom. An intermolecular cutoff of 12 Å was used for long-range electrostatic forces. The simulations were performed in the NVT ensemble using Langevin dynamics for temperature control. Induced dipoles were treated by the polarizable potential functions of the Amber molecular dynamics software.

All simulations began with an equilibrated cube of 900 H$_2$O molecules, with sides of length 30 Å. The long axis of each simulation cell (the axis normal to the water surface) was then lengthened to 120 Å, and the systems were further equilibrated for 10 ns. The simulations all employed periodic boundaries to create an “infinite-slab” geometry. After equilibrating the neat-H$_2$O slabs, two types of systems were created by introducing SO$_2$: a single-SO$_2$ system, herein referred to as the “neat-water” system, and a “saturated” SO$_2$ system with many gaseous surface and bulk-water SO$_2$ molecules.

The low and high concentration simulated systems, “neat-water” and “saturated”, respectively, were created as follows: the neat-water simulation involved the addition of a single SO$_2$ molecule either within the bulk of the water slab (for equilibrium MD), or above the slab surface (in the SMD simulations). The single-SO$_2$ neat-water system was then evolved for 2 ns to produce an equilibrated starting configuration. Because of the extremely low concentration of SO$_3$ in the neat-water system, the surface waters behave similarly to a true neat-water air—liquid interface. The neat-water system orientational results shown later in this work reproduce well the results of our previous orientational studies of surface water behavior. The saturated system had 22 SO$_2$ molecules introduced to the water slab bulk in order to saturate it to a level coinciding with the Henry’s law constant for SO$_2$ in water (k$_{H}$ = 1.4 mol/kg·bar). Additionally, 50 SO$_2$ molecules were introduced into the gas phase outside of the saturated water slab to simulate an added SO$_2$ gas pressure. The additional gas in the vapor phase was added over the course of several nanoseconds to keep a constant 1 atm of SO$_2$ pressure above the water surface as SO$_2$ gas molecules adsorbed to the surface. The saturated system with both bulk and gaseous SO$_2$ was then evolved for 2 ns to produce a starting configuration for further saturated simulations.

2.1. Equilibrium Molecular Dynamics Simulations. Equilibrium simulations involved adding SO$_2$ to a water slab and equilibrating as outlined above. The neat-water system had a single SO$_2$ added to the center of the water box, representing a concentration of 0.06 M. The more concentrated “saturated” system consisted of 22 SO$_2$ molecules in the bulk corresponding to a concentration 1.35 M. This saturated system was exposed to an additional 50 SO$_2$ in the gas phase above the water surface. After equilibration for 2 ns, both the low and high concentration systems were then evolved for a further 10 ns data collection using a time step of 0.5 fs, with atomic coordinates recorded every 100 fs.

2.2. SMD Simulations. A second set of simulations began with an equilibrated water slab as in the surface equilibrated method above. However, in both the neat-water and saturated starting systems, a single SO$_2$ was introduced 20 Å above the water slab surface, with the sulfur atom tethered to its initial position. The systems were then evolved for 1 ns, taking coordinate snapshots every 20 ps to create 50 starting points for further simulations. SMD was then performed on the 50 system configurations (in both the neat-water and saturated configurations) to guide the SO$_2$ down toward a tethered water near the water slab’s center of mass by applying a small steering force to the SO$_2$-sulfur atom. This steering technique has been previously developed and used to successfully model chemical events. The SO$_2$ thus passed through the continuum of environments from gas phase to (neat- and saturated) water surface adsorption, and finally absorption into the bulk of the H$_2$O slab. Each of the SMD simulations were performed for a total of 200 ps, using a time step of 1 fs, and taking snapshots of the system every 25 fs. Figure 1 illustrates two sample starting configurations for the SMD simulations, showing both the neat-water slab and the saturated slab configurations before steering the SO$_2$ toward the water bulk.

A separate set of SMD simulations were performed with tethering of one of the SO$_2$-oxygens to the water slab center of mass. This was done to ensure that the orientation of the SO$_2$ during the adsorption transit was not an artifact of the choice of atom used for tethering. The simulations produced the same results (not shown) for the orientational analyses, so the data from the original tethering scheme was used.

2.3. Aqueous Surface Location. The first portion of the studies involved creating orientational depth-profiles in the interfacial region comprised of SO$_2$ and H$_2$O upon exposure and adsorption of the gas. Recognizing that a liquid surface is a dynamic boundary that is neither flat nor stationary, we must define a reference point in the interfacial region which we refer to
here as the water surface location. Several previous studies have
used the technique of fitting a line shape to the averaged density
profile of the water, and extracting interfacial shape and location
parameters to define the water surface location.\textsuperscript{35-37} Hyperbolic
tangent functions have been used often, and values for the “Gibb’s
dividing surface” location and interfacial width have thus been
determined.\textsuperscript{38} However, in long simulations the location and shape
of the interface change, and the motion of surface waters alters the
interfacial width at any given time step. Thus, the density profile
fitting will capture averaged widths and locations, not instantaneous
values. Similarly, the averaged values of location and width will
obscure information about any drift or deformations the surface
undergoes. The analysis presented here attempts to retain these
subtleties through the use of a “corrected” coordinate system.

Figure 2 demonstrates the problem of surface location drift
during a simulation (even with utilizing the Amber NSCM parameter).
Figure 2A shows the density profile of water and SO\textsubscript{2} over the course of one of the 10 ns trajectories used in this
work using the original uncorrected coordinates of the system
taken from the raw atomic positions of the molecular dynamics
data output. The water density profile and location (thin gray line
in Figure 2A) is produced by averaging the instantaneous density
profile at each time step in the simulation over all the time steps.
The water profile was then fit to a tanh function (black line) to
extract the position and width parameters of the water surface.
The fitted surface water density profile has a width of 3.77 Å, which is comparable to values reported for similar neat-water
systems.\textsuperscript{27,39} A bulge in the gas-phase (≤5 Å) side of the water

Figure 1. Sample starting configurations for the two types of SMD simulations. The neat-water slab simulation introduces a single SO\textsubscript{2} molecule that is
then guided into the surface of the water and further into the bulk (left). The saturated slab simulation begins with a water system that has been loaded
with SO\textsubscript{2} to saturate the water phase, and also with a high pressure of SO\textsubscript{2} gas (right). The single SO\textsubscript{2} (shown at the top) is then steered through the
surface region saturated with SO\textsubscript{2} molecules, and into the water bulk.
density profile is indicative of the drift of the water slab over the course of the trajectory. Thus the calculated location and width from the tann line fit are not accurate over long trajectories for defining a stationary reference point.

To overcome this problem, we define the water surface location by calculating a reference location at each time step by averaging the positions of the waters contained in the topmost monolayer. This provides a consistent and intuitive reference point in the simulations to which we relate our analyses, but does not increase the computational burden. The number of waters included in the averaging is determined by taking a few issues into account. First, counting the waters found in the topmost cross-section of the water slab over several time steps indicated between 65 and 75 waters that established a full monolayer. This was done by a visual inspection of the slab using the VMD MD visualization package. Alternatively, assuming a spherical model of water with a radius of 2.2 Å, two layers of hexagonally tightly-packed spheres yielded a similar number of surface water molecules. Increasing the number of waters used in calculating the surface location diminishes the effects of the few waters that briefly rise above the surface into the gas phase, stabilizing both the surface position and thickness values. Taking the close-packed model as a maximum number of waters fit into a flat surface, the topmost 70 water molecules were used for calculating instantaneous water surface locations for each simulation step.

This method for finding the outer monolayer location was implemented, and the surface location is plotted as a function of simulation time in Figure 2B. It is apparent from the surface location plot that the water slab location, and thus the surface location, drifts over the 10 ns, spanning approximately 12 Å. However, the maximum standard deviation of the positions of the waters comprising the surface layer at each time step is only 1.85 Å. Consequently, all depth locations in our analyses are calculated relative to the instantaneous surface location at the corresponding time step of the trajectories.

2.4. Molecular Orientation. Knowing the molecular orientation of both the H2O and SO2 is a prerequisite for understanding the chemistry occurring during the SO2 adsorption process. With the surface location as defined above, the simulated systems were analyzed to characterize the orientation of H2O and SO2 in various environments above, within, and below the aqueous surface region. The two molecules studied are similarly shaped with a C2v axis along their bisectors, and a molecular plane defined by three atoms. A body-fixed frame is defined for both H2O and SO2 as shown in Figure 3. In each analysis a space-fixed reference axis is used that corresponds to the long axis of the system’s periodic cell normal to the plane of the water surface. The orientational analyses presented herein focus on two angles used to define molecular orientation. The molecular orientation angles \( \theta \) and \( \phi \) are determined from a set reference axis as shown in Figure 4A.

The “tilt” angle, \( \theta \), defines the angle formed between the molecular bisector vector (the molecular z-axis, pointing from the central atom in the direction of the other two atoms) and the positive system reference axis. Thus the value of \( \theta \) falls within a range of \([0^\circ, 180^\circ]\). An angle of \( \theta = 0^\circ \) indicates a molecule with its bisector aligned with the reference axis, while \( \theta = 180^\circ \) results from an antialigned configuration. Sample representations of molecular orientations resulting from different values of \( \theta \) are shown in Figure 4B.

A second angle, \( \phi \), defines the molecular “twist” of the molecule. \( \phi \) is the angle of rotation around the molecular bisector axis that quantifies the rotation of the molecular plane with respect to a plane perpendicular to the water surface. The values of \( \phi \) fall in the interval \([0^\circ, 90^\circ]\) because of the symmetry of H2O and SO2 molecules with respect to twist about their bisector axes. For values of \( \theta \approx 90^\circ \), \( \phi \) provides additional information about whether the molecular orientation is “flat” to the surface (e.g., the plane of the molecule is aligned with the plane of the surface), or if it is perpendicular. The values of \( \phi \) for different molecular orientations are depicted in Figure 4C. Values of \( \theta \) close to 0° or 180° result in an isotropic distribution in \( \phi \) because of the symmetry of the plane of the surface in directions perpendicular to the surface normal reference axis.

2.5. Surface Density Distributions. One measure of surface activity is the spatial distribution of molecules in the interfacial region. The density distributions of both H2O and SO2 were calculated for the equilibrium MD simulations. The results presented in Figure 5 show both the water (black) and SO2 (red) density distributions, averaged over two simulated interfaces of each slab. As shown, the single SO2 in the neat-water system

Figure 3. Molecular body-fixed axes are defined with the \( x-z \) plane formed by the three atoms, and the \( z \)-axis aligned to the molecular bisector. The \( y \)-axis is normal to the molecular plane, and one of the bonds points in the positive \( x \) direction.

Figure 4. (A) The definition of the angles \( \theta \) and \( \phi \) used to define molecular orientation of SO2 and H2O relative to a reference axis. (B) \( \theta \) is the value of the “tilt” of the molecular \( \phi \) relative to a reference axis, with \( \theta \) values ranging from \( 0^\circ \) (aligned) to \( 180^\circ \) (antialigned). \( \theta = 90^\circ \) aligns the bisector parallel to the plane of the water surface. Several molecular orientations are shown depicting different \( \theta \) values. (C) \( \phi \) is the “twist” angle defined as a rotation around the molecular bisector axis. A value of \( 0^\circ \) aligns the plane of the molecule perpendicular to the plane of the water surface. A value of \( 90^\circ \) rotates the molecule to lie flat in the plane of the water surface. Because of the symmetries of SO2, H2O, and the plane of the water surface, the range of \( \phi \) values is limited to \( 0^\circ \leq \phi \leq 90^\circ \).
remained at the water slab surface. The SO$_2$ in the saturated system accumulated mostly at the surface, but some residual SO$_2$ remained well into the bulk water.

In the simulated neat-water slab, the SO$_2$ molecular density distribution concentrates near the water surface location, indicating an affinity for the interfacial region. During the course of the simulation, the SO$_2$ does not venture into the bulk water, nor does it escape the water surface into the gas phase, but remains located within 5 Å of the surface region. This is consistent with what is found experimentally in our laboratory using VSFS, and also supported by the computational simulations and spectral calculations of Baer et al. The experimental studies indicated that upon exposure of SO$_2$ to a H$_2$O surface, a layer of solvated SO$_2$ forms, modifying the structure of water in the upper surface region. In the experimental system, the SO$_2$ bonding interaction with the free OH oscillators is manifested in a redshift of the free OH frequency indicative of a bonding interaction.

Figure 5. Molecular density distributions of H$_2$O (black) and SO$_2$ (red) calculated along the long-axis of the simulated cells. The position axis shows the distance from the instantaneous surface location of the H$_2$O slab, with positive values located above the slab toward the gas phase, and negative values located in the water bulk. Distributions of both the neat-water simulation with a single SO$_2$ (left, with the SO$_2$ density scaled 10$^x$ for clarity), and the saturated system (right) are shown.

The saturated solution simulation results indicate that under the high concentration of SO$_2$, the SO$_2$ accumulation at the surface is increased. However, unlike the neat-water slab, the saturated slab has a nonzero bulk concentration of SO$_2$. The added concentration of SO$_2$ creates a layer of molecules bound to the top of the water surface. The center of the SO$_2$ density distribution is further into the gas phase than that for the neat-water surface with a single-SO$_2$ molecule. Additionally, the water profile is broader in the saturated system. This indicates that water penetrates into the SO$_2$ layer, and moves further into the gas phase than under the neat-water conditions. Because of the limitations of the classical model in accurately reproducing the first hydration shell around the SO$_2$, we do not draw specific conclusions about the hydrated surface complex’s geometry. However, the surface affinity of the hydrated SO$_2$ is well reproduced by both the classical and ab initio methods.

2.6. Equilibrated MD. Geometric analyses were performed to characterize the net molecular orientation of H$_2$O and SO$_2$ molecules at different depths from the water surface location. At each distance from the surface location, an orientation profile was created for both the H$_2$O and SO$_2$ molecules. The bivariate orientation distributions for the angles $\theta$ and $\phi$ at various depths were combined to form the intensity plots that show how the molecular orientation distributions change with distance to the surface location. These plots (Figures 6, 7, and 8) allow for a visual interpretation of how the net orientations are affected when moving from the gas phase through the interfacial region and to the surface location, and then further into the aqueous interfacial region and bulk. Both the neat-water, with only a single SO$_2$ introduced, and the high-concentration saturated system were analyzed. In the case of the neat-water system, the introduction of a single SO$_2$ does not greatly affect molecular orientation of water molecules in the interfacial region. These results of the water orientation are very similar to a neat-water system without any adsorbed solutes (not shown).

The depth profile plots are arranged as a grid of two-dimensional (2D) histograms. Each histogram is calculated for all molecules falling within a particular depth in the water interfacial region. The depth of each plot is marked (in Å) in the upper-right, with the water surface location set at 0 Å, positive depths lie on the gas-phase side of the surface, and negative depths are on the bulk water side. The horizontal axes of each histogram represent $\theta$ values, and the vertical axes represent $\phi$ values. Areas of low intensity appear in dark blue, and highest intensity in dark red. Regions of the plots where the intensity (coloration) is equally distributed along either the vertical or horizontal axes are considered isotropic in $\phi$ or $\theta$, respectively. Likewise, areas of the plot with high intensity over a small orientational range are considered to exhibit an orientational preference at the given depth. The angle distributions from both simulated slab surfaces were averaged for all the orientation analyses.

2.6.1. H$_2$O Orientation. The orientation depth-profiles for H$_2$O are shown in Figure 6 for both the neat-water (top) and saturated (bottom) systems during the equilibrium MD simulations. The interfacial region for both these calculations and the VSF experiments is defined as the region where molecular orientational anisotropy exists around the surface water location. Fitting the water density profiles we have calculated an interfacial width of approximately 10 Å for the neat-water system, and approximately 16 Å for the saturated system. In both systems the strongest orientational preference is found at the slab surfaces (positions near 0 Å). Previous work on orientational preference of water at air surfaces shows the same trend as our neat-water results. The swaths of coloration indicating high intensity appearing in the neat-water plots from −4 to +4 Å (and the corresponding regions in most of the saturated system plots) show the overall preference of water to orient at the surface. The
plots of the neat-water and saturated systems are similar to each other with a narrow region of reorientation, but the effect in the interfacial region is greater in the neat-water system as evidenced by the sharper transition in intensity from blue to red, compared to the saturated system that has a less pronounced intensity change over larger areas of the histograms.

The bisector tilt of the water molecules, \( \theta \), concentrates around \( \theta = 90^\circ \) within the first few Å above and below the water surface location, becoming progressively isotropic further through the interfacial region and into the water bulk of both systems. Above the surface location at positive distances, \( \theta \leq 90^\circ \) indicates that the water hydrogens tend to point toward the gas-phase side of the surface. As the tilt nears \( \theta = 90^\circ \) the \( \text{H}_2\text{O} \) bisector lies within the plane of the surface indicating a water orientation either flat on the surface, or with some amount of "twist" sending the OH bonds in tower, or out of the bulk. The value of \( \phi \) determines the "twist" in this case. Both systems show a similar trend where waters at or just below the surface have values of \( \phi \) near \( 90^\circ \), and waters above the surface take on values of \( \phi \) near \( 0^\circ \). This jump in the angular distribution of \( \phi \) indicates that waters at or below the surface lie mostly flat in the plane of the interface, and as they move above the surface toward the gas phase, they reorient with one OH bond pointing toward the water bulk, and one pointing out of the surface into the gas. This behavior is more strongly pronounced in the neat-water system where most of the surface waters are not interacting with an adsorbed layer of \( \text{SO}_2 \) molecules.

Although the plots show overall similarities for both the neat-water and saturated systems, the presence of a layer of adsorbed \( \text{SO}_2 \) molecules alters the orientation of those waters furthest into the gas phase. For the saturated solution, the resulting orientation of waters above 0 Å, shown in the bottom set of plots of Figure 6, is nearly isotropic in \( \phi \), and with \( \theta \leq 90^\circ \). This results from waters with bisectors pointing further into the adsorbed

Figure 6. Molecular orientation histograms of \( \text{H}_2\text{O} \) throughout the surface equilibrated systems. The depth (in Å) of each histogram within the water interface is numbered in the upper-right of each respective plot. The water surface location is set at a position of 0 Å with negative distance values located in the bulk of the slab, and positive distances toward the gas phase. Each histogram is a bivariate angle distributions for \( \theta \) (horizontal axes) and \( \phi \) (vertical axes) in both the neat- \( \text{H}_2\text{O} \) system (top) and the saturated system (bottom). Regions of high intensity are dark red, and low intensity are dark blue.
The SO$_2$ gas layer and both hydrogens pointing outward from the aqueous bulk. The effect is more pronounced as the waters move further from the water surface, and above 4 Å the $\theta$ distribution is mostly concentrated around $\theta = 0^\circ$ (see Figure 4).

The angle distributions above 6 Å in the neat-water plots of Figure 6 are mostly isotropic (manifested as uniform coloration throughout the range of orientations). Furthermore, there are few data points that make up the histograms, a result of fewer waters venturing beyond those extents. Conversely, waters near a layer of adsorbed SO$_2$ venture further above the water surface location relative to the low SO$_2$ concentration, where they can have interactions with the adsorbed SO$_2$ gas molecules. The waters above the water surface location orient perpendicularly to the interface. This is consistent with our recent experimental VSFS studies, which showed evidence for the reorienting behavior of water due to the SO$_2$ interactions with the topmost surface waters.$^{20}$

The distribution of $\phi$ is more sharply defined (i.e., less isotropic) for the neat-water system than for the saturated one. Waters on the neat surface lie flat or perpendicular to the surface if they are below or above the water surface location, respectively. The presence of the SO$_2$ allows a greater range of “twist” for those waters in the plane of the interface. The $\phi$ distributions quickly become isotropic above the saturated water surface location, shown as a uniform coloration across $\phi$ for most values of $\theta$.

2.6.2. SO$_2$ Orientation. Orientation distributions of the adsorbed SO$_2$ molecules were created during the equilibrium simulations for both the neat-water and saturated systems. Figure 7 shows the 2D distributions of $\theta$ and $\phi$ (arranged similarly to the water orientation distributions plots in Figure 6). The SO$_2$ orientation data set for the neat-water system is much smaller, as only a single SO$_2$ molecule was simulated in the bulk. The resulting distribution plots are thus representative.
of the single surface active SO$_2$ molecule. The neat-water SO$_2$ molecule remains within a narrower region of the interface than the saturated system SO$_2$, but effective comparisons can still be drawn. Note that the depth range of the plots in Figure 7 is different for the neat-water and saturated systems, reflecting the surface mobility of the SO$_2$ molecules in the two systems.

In the interfacial region, the angular distribution of the single SO$_2$ (in the neat-water system) is concentrated primarily in $\theta < 90^\circ$. The peak of the distribution occurs at $\theta = 0^\circ$. This indicates that the SO$_2$ bisector points out of the water surface, with the sulfur atom pointing toward the aqueous bulk, and the two oxygens pointing into the gas phase. This same distribution occurs in the saturated system for depths below the surface location, $< 0$ Å. Beyond 4 Å above the surface, both distributions become mostly isotropic, either because the SO$_2$ does not venture into the gas in the neat-water system, or because of the nature of the adsorbed SO$_2$ layer in the saturated system. Promixity to the water surface highly orients the SO$_2$ bisector.

The distributions of $\phi$ are isotropic in both systems at all depths. Because the SO$_2$ bisector near the surface is oriented perpendicularly to the interface, the isotropy in $\phi$ is expected. Further from the water surface where the bisector orientation becomes isotropic, the $\phi$ distribution remains isotropic. For the surface SO$_2$ orientation, the $\phi$ angle does not provide further information regarding the surface behavior or orientational preference.

2.7. SMD Transit Simulations. 2.7.1. SO$_2$ Orientation. The orientation of SO$_2$ molecules throughout the aqueous adsorption process was monitored during the transit SMD simulations. The angles $\theta$ and $\phi$ of the transiting SO$_2$ (Figure 4) were calculated for each time step of the SMD simulations as the SO$_2$ was pulled into the water slab from the gas phase, both in the neat-water and saturated slab systems. The orientation depth-profiles were collected for the 50 simulations of both systems for various distances from the water surface location, resulting in the 2D angle and depth-profile histograms shown in Figure 8.
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From its starting position above the water surface, until the SO₂ moves to within 6 Å of the water surface location of both systems, the orientation is isotropic in \( \theta \) and \( \phi \). Isotropic orientation is manifested in the plots as mostly uniform coloration at a given distance from the surface independent of \( \theta \) or \( \phi \). Near and into the interfacial region, the bisector angle \( \theta \) becomes more perpendicular to the water surface \( (\theta \approx 0^\circ) \) with the SO₂ sulfur pointing into the water phase, consistent with the equilibrium MD simulation results above. At the point when the SO₂ reaches the water surface location (0 Å), the bisector is perpendicular to the interface in both the neat-water and saturated systems. In the absence of simulated ionic species that form through SO₂–H₂O chemistry at the surface, it is clear that the adsorbing SO₂ in the gas phase takes on a preferred orientation to adsorb on a water surface. The main difference between the neat and saturated water systems is where the point of the transition from isotropic to preferred orientations is found.

Comparing in more detail the difference in these two systems upon SO₂ approach, for the neat-water surface, a transition occurs at approximately 4 Å above the water surface location. Below 4 Å above the surface, SO₂ has a preferred net orientation and is close enough to the water surface that it begins to interact with the topmost surface waters. In the saturated system, the same trend occurs; however, the onset of the perpendicular orientation begins at approximately 8 Å above the surface. The layer of adsorbed SO₂ already present in the saturated system most likely interacts with the transiting SO₂ molecule. Also, topmost water molecules from the surface move up to a few angstroms inside the adsorbed SO₂ layer and interact with the transiting SO₂ further from the surface than those in the neat-water system. It is remarkable that the orientational trend appears so strongly in the \( \theta \) plots even with so little data as was collected from the single SO₂ molecule of each simulation. From the onset of orientation above the surface until 10 Å below (not shown), the SO₂ holds a preferred orientation.

With a mostly perpendicular bisector angle, it is expected that the values of \( \phi \) for SO₂ would be isotropic relative to the reference axis. This is the case in both systems, with only a few exceptions. In both systems, the \( \phi \) profiles exhibit mostly isotropic distributions above 0 Å, with several regions of lighter coloration interspersed, but without a clearly formed orientational trend. At the neat-water surface and just above (from 0 to 2 Å above the water phase), the \( \theta \) profile broadens to \( \theta = 90^\circ \), near \( \phi = 90^\circ \) appearing as a shoulder of light coloration in the bottom-left of the 0–2 Å axes. This indicates that SO₂ inclined up to 90° from the surface normal will have a preferred \( \phi \) orientation lying more flat to the water surface. This is in contrast to SO₂ molecules above the water surface location, oriented more perpendicularly and without a preference for a particular range of values in \( \phi \). The behavior is likely due to the interaction between the waters and the S–O bonds leading to a higher solvation than above the water surface location. As the SO₂ is solvated by more highly coordinated bulk water, the S–O bonds experience less equal interaction environments. Baer et al. noted that their force field model for the SO₂ does not reproduce the first hydration shell geometries well, so conclusions regarding the specific interactions and hydrate geometries between the SO₂ and H₂O cannot be made here. It is notable that the same reorientation does not occur as strongly in the saturated system. The presence of the adsorbed SO₂ layer apparently decreases the reorienting behavior likely because of the disrupting effect the higher SO₂ concentration has on the water interactions in the interfacial region.

3. CONCLUSIONS

Gaseous adsorption on solid surfaces has been extensively studied over the past few decades with much learned about how molecular geometry and orientation of the adsorbate are influenced by the proximity of the solid slab. For a liquid surface where the surface slab is no longer rigid but has molecules with considerable freedom of movement, the surface and approaching gas molecules can be active partners in attaining the optimal geometry and orientation necessary for adsorption and subsequent uptake. And unlike the solid surface defined by a sharp plane, the interfacial region for the liquid–gas system is much broader, extends on either side of a defined center plane, and is host to a broad distribution of gas–liquid molecular geometries and orientations that change as the gas molecules transit through.
the interfacial region into the bulk liquid. Although our current molecular level understanding of the complex roles that these molecules play in this fluid interfacial region is in its infancy, emerging studies such as these are beginning to provide unique new insights that are key to understanding many environmentally important processes at aqueous surfaces.

Presented herein are the results of several classical molecular dynamic simulations that focus on understanding how surface water molecules and adsorbing SO2 gas molecules twist and turn as the gas adsorbs and transits the interfacial region. The computational studies emulate and expand on the experimental spectroscopic studies from this laboratory that have found SO2 surface complexation at a water surface.17,18,20 These spectroscopic studies show clear evidence of SO2−water surface complexation, but details about this surface complex could only be inferred from spectral changes in the surface water spectrum since SO2 could not be monitored directly. These simulations do not have that limitation and hence can provide information about the behavior of both surface partners and, in particular, how their proximity influences the orientation behavior of each other. The orientational information obtained in these simulations are provided via calculated depth profiles that show the molecular distribution of orientations of the two different interfacial molecules throughout the dimensions of the interfacial region.

Our simulations show that gaseous SO2 quickly adsors to the water surface and continues to bind until a complete surface coverage is reached. Surface waters reorient in the presence of adsorbed SO2. The waters at and just below the interface of a neat-water surface tend to lay flatter to the surface than when a saturating layer of SO2 is present. The waters above the surface location or interacting with the layer of adsorbed SO2 orient more perpendicularly to the interface, and further expose their “free=OH” uncoupled bonds for interactions with SO2 and hydrate complex formation. Furthermore, we have found that surface waters underneath a blanket layer of adsorbed SO2 will penetrate further into the gas phase, allowing for greater mobility of waters away from the aqueous bulk in the presence of SO2.

Through these simulations we also characterize the orientational behavior of SO2 during and after adsorption. Our equilibrium neat-water simulations show that a single SO2 molecule, representing a low concentration, has a high surface affinity. At a high SO2 concentration in the saturated systems, SO2 molecules are also surface active, and are found further out of the water phase than at the lower concentration. These SO2 molecules form a bound layer that crowds the surface and interacts with the surface waters. The orientation of SO2 on the water surface was found to be similar for both low and high concentrations. Those SO2 molecules at or below the surface water location strongly orient with the sulfur atom pointed in toward the water bulk, and the oxygen atoms pointed out toward the gas phase. The SO2 molecules slightly above the water surface lose this net orientation within 6–8 Å. Those molecules further from the water are more isotropically oriented. Figure 9 depicts what the neat-water and saturated surface molecules look like for both SO2 and H2O orientations and locations based on the calculations.

SMD simulations were used to model the behavior of an adsorbing SO2 as it moves from the gas phase above the water down through the surface and into the bulk. The SO2 reorients as it makes its first contact with the water interface. Within 4 Å of the surface, the SO2 is mostly oriented with its sulfur toward the water phase. The results for the transit through the interface show that in both systems of low and high SO2 concentration, an adsorbing SO2 near the interface has very similar orientation to those molecules already bound to the water surface. The SO2 pulled further into the water bulk retains its orientation until it is past the interfacial region and then isotropically orients with the bulk water.

These studies provide a starting point for future studies in this area that seek to understand how gases of different concentrations and chemical composition adsorb and transit across an aqueous/air interface. Obtaining such knowledge will be invaluable for understanding many environmental aerosol and land water systems where gaseous uptake at a water surface does not conform to expectations.9,11,16,41 Investigations of these and related low-temperature effects will be forthcoming in future publications.

**ASSOCIATED CONTENT**

Supporting Information. The radial distribution functions of the water-SO2 along with the interaction energy of the H2O−SO2 system as a function of the S−O distance. This material is available free of charge via the Internet at http://pubs.acs.org.

**REFERENCES**


ARTICLE

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