

Problem Set 1: SOLUTIONS

1.a. the motion equation is

$$m\ddot{x} = -kx \quad \omega = \sqrt{k/m}$$

that is $\ddot{x} + \omega^2 x = 0$

if $x = A \sin \omega t + B \cos \omega t$.

then $\dot{x} = A\omega \cos \omega t - B\omega \sin \omega t$.

$$\begin{aligned} \text{so } \ddot{x} &= -A\omega^2 \sin \omega t - B\omega^2 \cos \omega t \\ &= -\omega^2 (A \sin \omega t + B \cos \omega t) \end{aligned}$$

$$\therefore \ddot{x} + \omega^2 x = (A \sin \omega t + B \cos \omega t)(\omega^2 - \omega^2) = 0.$$

so $x(t) = A \sin(\omega t) + B \cos(\omega t)$ is a solution to the equation.

1.b. if $x(t) = C \sin(\omega t - \varphi)$

then $\dot{x}(t) = \omega C \cos(\omega t - \varphi)$

$$\ddot{x}(t) = -\omega^2 C \sin(\omega t - \varphi)$$

$$\text{so } \ddot{x}(t) + \omega^2 x = -\omega^2 C \sin(\omega t - \varphi) + \omega^2 C \sin(\omega t - \varphi) = 0$$

$\therefore x(t) = C \sin(\omega t - \varphi)$ is also a solution.

1.c. if $x(t) = D \sin \omega t + E \cos(\omega t - F)$

then $\dot{x}(t) = D\omega \cos \omega t - E\omega \sin(\omega t - F)$

$$\ddot{x}(t) = -\omega^2 D \sin \omega t - \omega^2 E \cos(\omega t - F)$$

$$= -\omega^2 (D \sin \omega t + E \cos(\omega t - F))$$

$$= -\omega^2 x(t)$$

$$\text{so } \ddot{x}(t) + \omega^2 x(t) = -\omega^2 x(t) + \omega^2 x(t) = 0.$$

so his $x(t)$ is also a solution to the differential equation.

we have $x(t) = D \sin \omega t + E \cos(\omega t - F)$

$$= D \sin \omega t + E (\cos \omega t \cos F + \sin \omega t \sin F)$$

$$= D \sin \omega t + E \cos F \cos \omega t + E \sin F \sin \omega t$$

$$= (D + E \sin F) \sin \omega t + E \cos F \cos \omega t$$

if we set. $A = D + E \sin F$

$$B = E \cos F$$

then $X(t) = A \sin \omega t + B \cos \omega t$

So we only need two arbitrary parameters.

2. a. $f(x) = \sum_{n=0}^{\infty} \frac{1}{n!} f^{(n)}(x) x^n$

$$\begin{aligned} \text{So } \sin x &= \frac{1}{0!} \sin(0) x^0 + \frac{1}{1!} \cos(0) x^1 + \frac{1}{2!} (-\sin x)|_{x=0} x^2 \\ &\quad + \frac{1}{3!} (-\cos x)|_{x=0} x^3 + \frac{1}{4!} (+\sin x)|_{x=0} x^4 + \frac{1}{5!} (\cos x)|_{x=0} x^5 + o(1) \\ &= x - \frac{x^3}{3!} + \frac{x^5}{5!} + o(1) \end{aligned}$$

b. $y(x) = \frac{1}{\sqrt{x}} + x$

$$y'(x) = -\frac{1}{2} \frac{1}{x\sqrt{x}} + 1 = 0$$

$$\therefore x^{\frac{3}{2}} = \frac{1}{2}$$

$$x = \sqrt[3]{\frac{1}{4}}$$

when $0 < x < \sqrt[3]{\frac{1}{4}}$ $y'(x) < 0$

when $x > \sqrt[3]{\frac{1}{4}}$ $y'(x) > 0$

So at $x_0 = \sqrt[3]{\frac{1}{4}}$ $y(x)$ is minimal.

$$y'(x) = -\frac{1}{2} x(-\frac{3}{2}) x^{-\frac{5}{2}} = \frac{3}{4} x^{-\frac{5}{2}}$$

$$y^{(3)}(x) = \frac{3}{4} x(-\frac{5}{2}) x^{-\frac{7}{2}} = -\frac{15}{8} x^{-\frac{7}{2}}$$

$$\therefore y''(x_0) = \frac{3}{4} x \left(\frac{1}{4}\right)^{\frac{1}{3}x^{-\frac{5}{2}}} = \frac{3}{4} x \left(\frac{1}{4}\right)^{-\frac{5}{6}} = 3x \left(\frac{1}{4}\right)^{\frac{1}{6}} = 3x 4^{-\frac{1}{6}}$$

$$y^{(3)}(x_0) = -\frac{15}{8} x \left(\frac{1}{4}\right)^{\frac{1}{3}x(-\frac{7}{2})} = -\frac{15}{8} x \left(\frac{1}{4}\right)^{-\frac{7}{6}} = -\frac{15}{2} x \left(\frac{1}{4}\right)^{-\frac{1}{6}} = -\frac{15}{2} x 4^{\frac{1}{6}}$$

$$\begin{aligned} \text{So } y(x) &= y(x_0) + \frac{1}{1!} y'(x_0)(x-x_0) + \frac{1}{2!} y''(x_0)(x-x_0)^2 + \frac{1}{3!} y^{(3)}(x_0)(x-x_0)^3 + o(1) \\ &= 4^{\frac{1}{6}} + 4^{-\frac{1}{3}} + \frac{1}{2} \times 3x 4^{-\frac{1}{6}} \left(x - \left(\frac{1}{4}\right)^{\frac{1}{3}}\right)^2 + \frac{1}{6} \times \left(-\frac{15}{2}\right) x 4^{\frac{1}{6}} \left(x - \left(\frac{1}{4}\right)^{\frac{1}{3}}\right)^3 + o(1) \end{aligned}$$

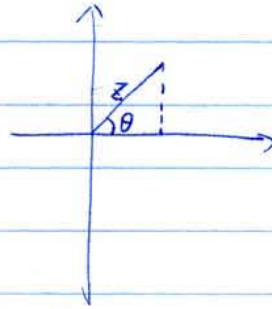
$$3. e^{j\theta} = \cos\theta + j\sin\theta$$

$$z e^{j\theta} = z \cos\theta + j z \sin\theta$$

$$|z e^{j\theta}| = \left(z e^{j\theta} \cdot (z e^{j\theta})^* \right)^{\frac{1}{2}}$$

$$= \left(z \cdot z^* \cdot e^{j\theta} \cdot e^{-j\theta} \right)^{\frac{1}{2}}$$

$$= |z|$$



so there is no alteration of the length.

if $z = a + jb$.

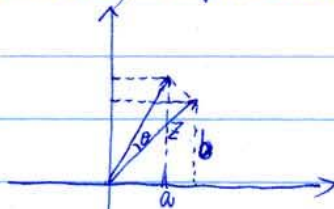
the pole angle of z is ~~the~~ ϕ

$$\tan\phi = \frac{b}{a}$$

$$z e^{j\theta} = (a + jb)(\cos\theta + j\sin\theta)$$

$$= a\cos\theta + a\sin\theta j + b\cos\theta j - b\sin\theta$$

$$= (a\cos\theta - b\sin\theta) + j(a\sin\theta + b\cos\theta)$$



set the new angle as ϕ'

$$\text{then } \tan\phi' = \frac{a\sin\theta + b\cos\theta}{a\cos\theta - b\sin\theta} = \frac{\left(\frac{a\sin\theta}{b\cos\theta} + 1\right) b\cos\theta}{\left(1 - \frac{b\sin\theta}{a\cos\theta}\right) a\cos\theta}$$

$$= \frac{\frac{\tan\theta}{\tan\phi} + 1}{1 - \tan\theta \tan\phi} \cdot \tan\phi$$

$$= \frac{\tan\theta + \tan\phi}{1 - \tan\theta \tan\phi} = \tan(\theta + \phi)$$

$\therefore \phi' = \theta + \phi$ so we show that multiplication of any complex number z by $e^{j\theta}$ ~~can~~ can be described as a positive rotation by θ .

$$4. \quad \cos jx = \cos x + j \sin x$$

$$\text{so } \cos x = \frac{1}{2}(e^{jx} + e^{-jx})$$

$$\sin x = \frac{1}{2j}(e^{jx} - e^{-jx})$$

$$\text{so } \sin(u \pm v) = \frac{1}{2j}(e^{j(u \pm v)} - e^{-j(u \pm v)})$$

$$= \frac{1}{2j}(e^{ju} \cdot e^{\pm jv} - e^{-ju} \cdot e^{\mp jv})$$

$$= \frac{1}{2j}((\cos u + j \sin u)(\cos v \pm j \sin v) - (\cos u - j \sin u)(\cos v \mp j \sin v))$$

$$= \frac{1}{2j}(\cos u \cos v + j \sin u \cos v + j \cos u \sin v \mp \sin u \sin v$$

$$- [\cos u \cos v - j \sin u \cos v \pm j \cos u \sin v \mp \sin u \sin v])$$

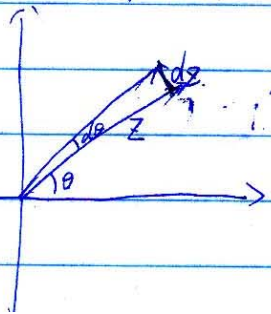
$$= \sin u \cos v \pm \cos u \sin v$$

$$5. \quad z = A e^{j\theta}$$

$$\text{then } dz = A de^{j\theta}$$

$$= A j e^{j\theta} d\theta$$

$$= j z d\theta$$



the direction of dz is perpendicular to that of vector $(\operatorname{Re} z, \operatorname{Im} z)$.

$$dz = z d\theta e^{j\frac{\pi}{2}}$$

$$= j z d\theta$$

6

We want to know how much $\$i^i$ is worth. We start by rearranging our given expression with the identity,

$$i = e^{\ln i}$$

So we have

$$i^i = (e^{\ln i})^i = e^{i \ln i}$$

Notice also that

$$i^{\frac{\pi}{2}} = \ln(e^{\frac{i\pi}{2}}) = \ln(\cos \frac{\pi}{2} + i \sin \frac{\pi}{2}) = \ln i$$

Plugging this result into the previous equation gives us

$$i^i = e^{i \ln i} = e^{i i^{\frac{\pi}{2}}} = e^{-\frac{\pi}{2}} = 0.21.$$

So $\$i^i$ is 21 cents. It's worth it!

Comment: Think about what $e^{i\pi/2}$ looks like graphically, in the complex plane – a 90° rotation!

7. a. $x = A \cos(\omega t + \alpha)$

when $t=0$ $x=0$

that is $A \cos \alpha = 0$ so $\alpha = \frac{\pi}{2} + k\pi$ $k=0, \pm 1, \pm 2, \dots$

$A = 5 \text{ cm}$

$T = \frac{1}{f} = 1 \text{ s} = \frac{2\pi}{\omega}$ so $\omega = 2\pi$

so $x = 5 \cos(2\pi t + \frac{\pi}{2} + k\pi)$

b. $t = \frac{8}{3}$

$x = 5 \cos(2\pi \times \frac{8}{3} + \frac{\pi}{2} + k\pi) = \frac{5\sqrt{3}}{2} \cos k\pi$

$\frac{dx}{dt} = -5 \times 2\pi \sin(2\pi t + \frac{\pi}{2} + k\pi)$

so when $t = \frac{8}{3}$

$\frac{dx}{dt} = -10\pi \sin(\frac{16\pi}{3} + \frac{\pi}{2} + k\pi) = 5\pi \cos k\pi$

$\frac{d^2x}{dt^2} = -20\pi^2 \cos(2\pi t + \frac{\pi}{2} + k\pi)$

so when $t = \frac{8}{3}$

$\frac{d^2x}{dt^2} = -10\pi^2 \sqrt{3} \cos k\pi = -10\sqrt{3}\pi^2 \cos k\pi$

9. a. $E = \int k \left(\frac{1}{r_1} + \frac{1}{r_2} \right)^2 dA$

where r_1 and r_2 has the dimension of L .

so $\left(\frac{1}{r_1} + \frac{1}{r_2} \right)^2$ has the dimension of L^{-2} .

and A has dimension of L^2 .

so $\left(\frac{1}{r_1} + \frac{1}{r_2} \right)^2 dA$ is dimensionless.

that is k has the same dimensions as Energy.

b. $F = \alpha r v \eta$ where α is a dimensionless constant.

dimensions of each parameter are.

$$F: MLT^{-2}$$

$$r: L$$

$$v: LT^{-1}$$

so the dimension of η is

$$MLT^{-2} \cdot L^{-1} \cdot L^{-1} T = ML^{-1} T^{-1}$$

that is η has dimensions of Mass / [Time x Length]

(c) We know from the previous part that $[\eta] = \frac{[M]}{[TL]}$ and $[\kappa] = [E] = \frac{[M][L]^2}{[T]^2}$. We want to solve for the exponents in the following equation,

$$[\tau] = [T] = [\lambda]^a [\kappa]^b [\eta]^c = [L]^a \left(\frac{[M][L]^2}{[T]^2} \right)^b \left(\frac{[M]}{[TL]} \right)^c.$$

This gives us three equations to solve corresponding to each unit

$$0 = b + c$$

$$0 = a + 2b - c$$

$$1 = -2b - c.$$

Solving these equations tells us $b = -c$, $a = 3c$, and $c = 1$. So,

$$\tau \propto (\text{dimensionless constant}) \frac{\eta \lambda^3}{\kappa}.$$

(d) If we added z to our list of parameters we would have another exponent, d , to solve for. However, z has the same units as λ so we still only have three fundamental units to make equations from. This gives us three equations and four unknowns,

$$0 = b + c$$

$$0 = a + 2b - c + d$$

$$1 = -2b - c.$$

We cannot solve for all of the unknowns. The closest we can get is

$$\tau \propto (\text{dimensionless constant}) \frac{\eta}{\kappa} \lambda^a z^{3-a}.$$

Side note: A full hydrodynamic theory treatment of this problem reveals $a = 6$ and $d = -3$.