

Problem Set 5: SOLUTIONS

(1) The bouncing man.

(a) We need to find ω_0 , which we know from earlier work equals $\sqrt{k/m}$. What is the spring constant, k ? Then the man is attached, the spring is extended by $x = 20\text{cm}$ from its un-stretched equilibrium; at this point

$$mg = kx, \text{ as we've seen before (problem set 2). Therefore } k = \frac{mg}{x} \text{ and } \omega_0 = \sqrt{k/m} = \sqrt{\frac{g}{x}}.$$

Numerically, $\omega_0 = 7$ radians/second.

(b) I drive the oscillator with a harmonic force $F = F_0 \cos(\omega t)$. What is F_0 ? I move my hand with an amplitude B , stretching and compressing the spring. The force conveyed by the spring is therefore kB , and so $F_0 = kB$. The *response* of the man is oscillation with an amplitude of $A = 8$ cm. We know that

$$A(\omega) = \frac{F_0}{k} \frac{\omega_0/\omega}{\sqrt{\left(\frac{\omega_0}{\omega} - \frac{\omega}{\omega_0}\right)^2 + \frac{1}{Q^2}}},$$

one of our many expressions for $A(\omega)$. At resonance ($\omega = \omega_0$), therefore, $A = \frac{F_0}{k} Q$. From above, $A = BQ$, and so $Q = A/B = 8\text{cm} / 0.5\text{cm} = \mathbf{Q=16}$.

(c) The approximate $\bar{P}(\omega)$ relation $\bar{P}(\omega) = \frac{\gamma F_0^2}{2m} \frac{1}{\left[4(\omega_0 - \omega)^2 + \gamma^2\right]}$. We're concerned with $\omega = \alpha\omega_0$,

$$\text{where } \alpha = 1.05. \text{ Rewriting, } \bar{P}(\omega) = \frac{\gamma F_0^2}{2m} \frac{1}{\omega_0^2 \left[4(1 - \alpha)^2 + \frac{1}{Q^2}\right]} = \frac{F_0^2}{2m\omega_0 Q} \frac{1}{\left[4(1 - \alpha)^2 + \frac{1}{Q^2}\right]}.$$

in all the numbers, $k = 4.9$ N/m, $F_0 = kB = 0.0245$ N, and $\bar{P}(\omega) = \mathbf{0.002}$ Watts. (You can check that the above expression is dimensionally correct.)

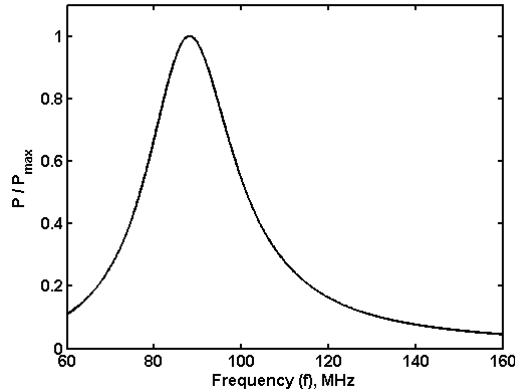
(2) Series RLC radio: As discussed in class and in the text, the maximum power absorption for a damped, driven oscillator occurs when the driving frequency (ω) equals the natural frequency (ω_0). (Keep in mind ω is the angular frequency, f is the "usual" frequency (cycles per unit time), and $\omega = 2\pi f$.) Also as discussed in class and in the text, $\omega_0 = \sqrt{1/(LC)}$ for a series RLC circuit.

(a) We want $\omega_0 = 2\pi \cdot 88.1$ MHz, using $C = 5$ pF. Therefore we need an inductor

$$L = \left(C\omega_0^2\right)^{-1} = 6.5 \times 10^{-7} \text{ H}.$$

(b) The width (in frequency) of the resonance of a series RLC circuit, as discussed in class and in the text, is $\Delta f = (1/2\pi)\Delta\omega \approx R/L$, i.e. $(1/2\pi) \times 100\Omega / (0.65 \times 10^{-6})\text{H} = 24$ MHz. In other words, the circuit will pick up the desired 88.1 MHz signal, as well as every station near it in a 24 MHz window. As you might realize

looking at an FM dial, there are lots of stations in this range!
 A plot of $P(f)$, the power absorption at various frequencies:



(3) Overdamped oscillator motion. We know that the general solution to the motion of an overdamped oscillator is $x(t) = A_1 e^{-\left(\frac{\gamma}{2} + \beta\right)t} + A_2 e^{-\left(\frac{\gamma}{2} - \beta\right)t}$. We are told that $x(t=0) = 0$ and $v(t=0) = v_0$. Therefore $x(t=0) = A_1 + A_2 = 0$, so $A_1 = -A_2$.

We could also note that the derivative $\dot{x}(t) = -A_1 \left(\frac{\gamma}{2} + \beta\right) e^{-\left(\frac{\gamma}{2} + \beta\right)t} - A_2 \left(\frac{\gamma}{2} - \beta\right) e^{-\left(\frac{\gamma}{2} - \beta\right)t}$, so $\dot{x}(t=0) = -A_1 \left(\frac{\gamma}{2} + \beta\right) - A_2 \left(\frac{\gamma}{2} - \beta\right) = A_2 \left(\frac{\gamma}{2} + \beta\right) - A_2 \left(\frac{\gamma}{2} - \beta\right) = 2A_2\beta = v_0$, and thereby solve for A_2 , but we'll see that this isn't even necessary for this problem.

Our particular solution $x(t) = A_1 \left[e^{-\left(\frac{\gamma}{2} + \beta\right)t} - e^{-\left(\frac{\gamma}{2} - \beta\right)t} \right] = A_1 e^{-\frac{\gamma}{2}t} \left[e^{-\beta t} - e^{+\beta t} \right]$. Clearly,

this is zero at $t=0$, as constructed. Is $x(t)=0$ anywhere else? The prefactor $e^{-\frac{\gamma}{2}t}$ is of course always positive (except at $t \rightarrow \infty$), so for $x(t)$ to be zero, we need $e^{-\beta t} - e^{+\beta t} = 0$, i.e. $e^{-\beta t} = e^{+\beta t}$. Taking logarithms, $-\beta t = \beta t$, which is satisfied only at $t=0$. So **no, $x(t)$ is never zero except at $t=0$, therefore the door never hits Mr. K.**

4. Driven oscillator response.

$$m\ddot{x} + b\dot{x} + kx = F_0 \cos \omega t.$$

$$\ddot{x} + \frac{b}{m}\dot{x} + \frac{k}{m}x = \frac{F_0}{m} \cos \omega t.$$

$$\ddot{x} + \gamma\dot{x} + \omega_0^2 x = F_0/m \cos \omega t.$$

$$\text{then } A(\omega) = \frac{F_0/m}{[(\omega_0^2 - \omega^2)^2 + (\gamma\omega)^2]^{1/2}}$$

(a) at $\omega = \omega_0$

$$A(\omega) = \frac{F_0/m}{\gamma^2 \omega^2}$$

$$\therefore \frac{dA(\omega)}{d\omega} = -2 \frac{F_0/m}{\gamma^2 \omega^3} < 0$$

\therefore at $\omega = \omega_0$, $A(\omega)$ is decreasing function.

$$(c) \tan \delta(\omega) = \frac{\gamma\omega}{\omega_0^2 - \omega^2} = \frac{\omega\omega_0}{Q(\omega_0^2 - \omega^2)}$$

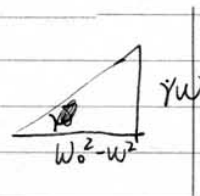
$$\therefore \frac{d(\tan \delta(\omega))}{d\omega} = \frac{d(\tan \delta)}{d\delta} \frac{d\delta}{d\omega}$$

$$= \frac{1}{\cos^2 \delta} \frac{d\delta}{d\omega} = \frac{d}{d\omega} \left(\frac{\omega\omega_0}{Q(\omega_0^2 - \omega^2)} \right)$$

$$= \frac{\omega_0 Q(\omega_0^2 - \omega^2) - \omega\omega_0 Q(-2\omega)}{Q^2(\omega_0^2 - \omega^2)^2}$$

$$= \frac{\omega_0(\omega_0^2 + \omega^2)}{Q(\omega_0^2 - \omega^2)^2}$$

$$\therefore \frac{d\delta}{d\omega} = \frac{\omega_0(\omega_0^2 + \omega^2)}{Q(\omega_0^2 - \omega^2)^2} \cos^2 \delta$$



$$\cos \delta = \frac{\omega_0^2 - \omega^2}{\sqrt{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2}} \quad \therefore \cos^2 \delta = \frac{(\omega_0^2 - \omega^2)^2}{(\omega_0^2 - \omega^2)^2 + \gamma^2 \omega^2}$$

$$\therefore \frac{dS}{dw} = \frac{w_0 (w_0^2 + w^2)}{Q (w_0^2 - w^2)^2} \cdot \frac{(w_0^2 - w^2)^2}{(w_0^2 - w^2)^2 + \gamma^2 w^2} = \frac{w_0 (w_0^2 + w^2)}{Q [(w_0^2 - w^2)^2 + \gamma^2 w^2]}$$

at $w = w_0$

$$\frac{dS}{dw} = \frac{w_0 \cdot 2w_0^2}{Q \gamma^2 w_0^2} = \frac{2w_0}{Q \cdot \frac{w_0^2}{Q^2}} = \frac{2Q}{w_0}$$

\therefore at $w = w_0$, $\frac{dS}{dw}$ is an increasing function of Q

(5)

French 4-14.

$$(a) \bar{p}(w) = \frac{F_0^2 w_0}{2kQ} \frac{1}{\left(\frac{w_0}{w} - \frac{w}{w_0}\right)^2 + \frac{1}{Q^2}}$$

when $w = 0.98 w_0$

$$\bar{p}(0.98 w_0) = \frac{F_0^2 w_0}{2kQ} \frac{1}{\left(\frac{1}{0.98} - 0.98\right)^2 + \frac{1}{Q^2}} = \frac{1}{2} \frac{F_0^2 w_0}{2kQ} \cdot \frac{1}{\frac{1}{Q^2}}$$

$$\text{that is } \left(\frac{1}{0.98} - 0.98\right)^2 + \frac{1}{Q^2} = \frac{2}{Q^2}$$

$$\therefore Q^2 = \frac{1}{\left(\frac{1}{0.98} - 0.98\right)^2}$$

$$Q = \frac{1}{\frac{1}{0.98} - 0.98} \doteq 24.75 \doteq 25$$

$$(b) Q = \frac{w_0}{\gamma}$$

$$\therefore \gamma = \frac{w_0}{Q} = \frac{w_0}{25} = 0.04 w_0$$

$$(c) \frac{\Delta E}{E} = \tau e^{-\gamma T} \doteq \tau (-\gamma T) = \gamma T = 0.04 w_0 \cdot \frac{2\pi}{w_0} = 0.08\pi \quad (Q \gg 1)$$