

# Lie Grps vs Lie Algs

Really important day!!

①

Thm 1:  $G, H$  are matrix Lie grps  $\mathfrak{g} = \text{Lie } \mathfrak{G}$   $\mathfrak{h} = \text{Lie } \mathfrak{H}$ . (Mathfunk font)

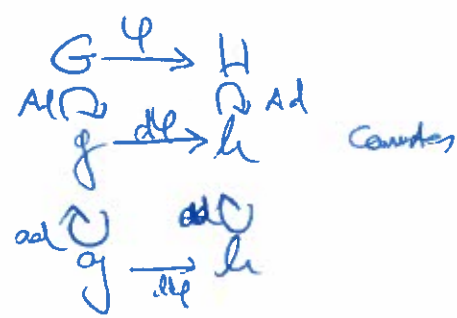
(B.18 Thm) Given  $\varphi: \mathfrak{G} \rightarrow \mathfrak{H}$  has  $d\varphi_x: \mathfrak{g} \rightarrow \mathfrak{h}$  a linear map. Then

①  $\varphi(e^x) = e^{d\varphi(x)} \quad \forall x \in \mathfrak{g}$

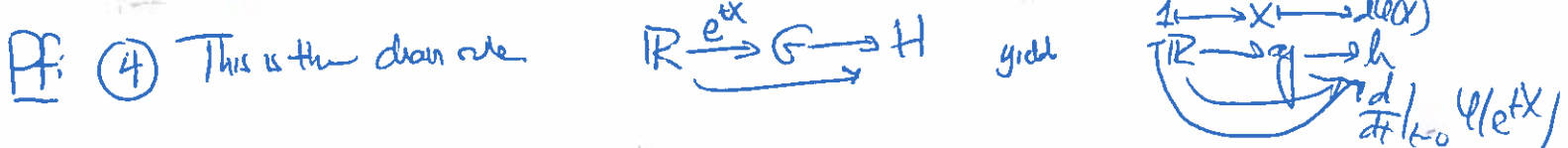
②  $d\varphi(AXA^{-1}) = \varphi(A) d\varphi(X) \varphi(A)^{-1}$   $A \in \mathfrak{G}$  i.e.

③  $d\varphi([X, Y]) = [d\varphi(X), d\varphi(Y)]$   $X, Y \in \mathfrak{g}$  i.e.

④  $d\varphi(X) = \left. \frac{d}{dt} \right|_{t=0} \varphi(e^{tX})$



And moreover,  $d\varphi$  satisfies the chain rule, i.e. if  $\mathfrak{G} \rightarrow \mathfrak{H} \rightarrow \mathfrak{K}$  then  $\mathfrak{g} \rightarrow \mathfrak{h} \rightarrow \mathfrak{k}$



Pf: ④ This is the chain rule.  $\mathbb{R} \xrightarrow{e^{tX}} \mathfrak{G} \rightarrow \mathfrak{H}$  yields  $\mathbb{R} \xrightarrow{t \mapsto X} \mathfrak{g} \xrightarrow{d\varphi} \mathfrak{h}$   
 ①  $t \mapsto \varphi(e^{tX})$  is a 1-param family so by thm of before,  
 it is  $t \mapsto e^{tZ}$  for some  $Z \in \mathfrak{h}$ . But then  $Z = \left. \frac{d}{dt} \right|_{t=0} \varphi(e^{tX})$   
 so by ④ it is  $d\varphi(X)$

Aside: If we didn't know about derivatives of smooth maps, we could use ① to define  $d\varphi$ .

Then we need to check that it is a linear map (chain rule is fairly obvious)  
 rescaling - not is easy.  $d\varphi(x+y)$  is  $Z$  s.t.  $e^Z = \varphi(e^{x+y}) = \varphi(\lim_{m \rightarrow \infty} (e^{\frac{x}{m}} e^{\frac{y}{m}})^m)$   
 $e^{d\varphi(x+y)} = \lim_{m \rightarrow \infty} (e^{\frac{d\varphi(x)}{m}} e^{\frac{d\varphi(y)}{m}})^m = \lim_{m \rightarrow \infty} (\varphi(e^{\frac{x}{m}}) \varphi(e^{\frac{y}{m}}))^m$

②  $\varphi(e^{AXA^{-1}}) = \varphi(Ae^XA^{-1}) = \varphi(A)\varphi(e^X)\varphi(A^{-1}) = \varphi(A)e^Z\varphi(A^{-1}) = e^{\varphi(A)Z\varphi(A)^{-1}}$

$Z = d\varphi(X)$

③  $[X, Y] = \left. \frac{d}{dt} \right|_{t=0} e^{tX} Y e^{-tX}$   $d\varphi$  linear so preserves derivatives  
 $d\varphi = \left. \frac{d}{dt} \right|_{t=0} d\varphi(e^{tX} Y e^{-tX}) = \left. \frac{d}{dt} \right|_{t=0} e^{t d\varphi(X)} d\varphi(Y) e^{-t d\varphi(X)} = [d\varphi(X), d\varphi(Y)]$

□

So get a map of  $g \rightarrow h$  w/ many nice properties. But it turns out the only really important one is  $\text{iv}$  (3), that it preserves the bracket! (2)

Thm 21 (Thm 5.33(1)) IF  $\varphi_1, \varphi_2: G \rightarrow H$  and  $d\varphi_1 = d\varphi_2$  then  $\varphi_1 = \varphi_2$ .  
 $G$  connected

Pf:  $\exists$  nbhd  $U$  of  $I \in G$  st. every  $g \in U$  is  $e^x$  for some  $x \in g$ .

~~By~~ By the same argument as before, we have

Lemma (Cor 3.26) If  $G$  is connected and  $U$  is a nbhd of  $I$  then every  $g \in G$  is in  $U^k$  for some  $k$ ,  $U^k = \{g_1 g_2 \dots g_k \mid g_i \in U\}$ .

Pf: Choose a path  $I \rightarrow g$ , use compactness + connectedness of  $[0,1]$ .

So every  $g \in G$  has the form  $e^{x_1} e^{x_2} \dots e^{x_k}$  for some  $x_i \in g$ .

Then  $\varphi_1(g) = \varphi_1(e^{x_1} \dots e^{x_k}) = \varphi_1(e^{x_1}) \dots \varphi_1(e^{x_k}) = e^{d\varphi_1(x_1)} \dots e^{d\varphi_1(x_k)}$

$\varphi_2(g) = \dots = e^{d\varphi_2(x_1)} \dots e^{d\varphi_2(x_k)}$   $\square$

Insect comes here

Thm 3<sup>rd</sup>: Suppose one has a map  $f: g \rightarrow h$  st.  $f([x,y]) = [f(x), f(y)]$ .

(Thm 5.33(2)) If  $G$  is connected + simply connected then  $\exists$  (! by above)  $G \xrightarrow{\varphi} h$  with  $d\varphi = f$ .

Pf: Let  $U$  be nbhd of  $I$  where  $\exp$  is diffeo. Define  $\varphi: U \rightarrow h$   
 $u \mapsto e^{f(\log u)}$

so  $d\varphi|_I = f$ . Let  $V$  be nbhd of  $0$  in  $g$  matching  $U$ .

Claim 1: If  $u_1, u_2, u_1 u_2 \in U$  then  $\varphi(u_1) \varphi(u_2) = \varphi(u_1 u_2)$ . "Local homomorphism"

Pf (BCH formula)  $u_1 = e^x, u_2 = e^y, u_1 u_2 = e^{x+y + \frac{1}{2}[x,y] + \dots}$   $\leftarrow$  some formula only needing brackets!!!  
 $x, y, x+y, \dots \in V$ .

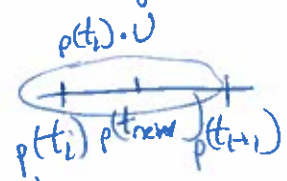
Then  $\varphi(u_1 u_2) = e^{f(x+y + \frac{1}{2}[x,y] + \dots)} = e^{f(x) + f(y) + \frac{1}{2}[f(x), f(y)] + \dots} = e^{f(x)} e^{f(y)} = \varphi(u_1) \varphi(u_2)$ .  $\square$

Now let  $p: [0,1] \rightarrow G$   $0 \mapsto I$   $1 \mapsto g$  be a path, and choose  $t_0=0, t_1, \dots, t_k=1$  s.t.  $p(t_i)p(t_{i-1})^{-1} \in U$  (exists by compactness argument)  
 For more precisely,  $p(s)p(t_{i-1})^{-1} \in U \quad \forall s \in [t_{i-1}, t_i]$  (Don't know  $U$ -reduction)

Now define 
$$\varphi_p(g) \equiv \varphi(p(t_k)p(t_{k-1})^{-1}) \varphi(p(t_{k-1})p(t_{k-2})^{-1}) \dots \varphi(p(t_1)I)$$

Claim 2: This depends on the path  $p$ , but not on the choice of times  $t_i$ .

Pf: Easy to show that inserting a new time doesn't change the answer. Then you can mutually refine two choices.



But  $\varphi(p(t_{i+1})p(t_i)^{-1}) = \varphi(p(t_{i+1})p(t_{i+1/2})^{-1}) \varphi(p(t_{i+1/2})p(t_i)^{-1})$  by local homomorphism.  $\square$

Claim 3: Homotopic paths have  $\varphi_p(g) = \varphi_q(g)$ .

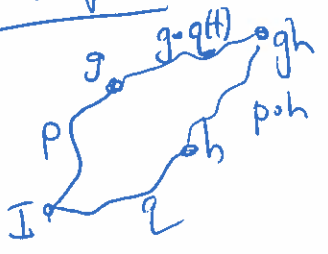
Pf: One can deform paths slowly by adjusting w/ little squares inside  $U$  translates.



then  $\varphi(yx^{-1}) = \varphi(yz_1^{-1}) \varphi(z_1x^{-1}) = \varphi(yz_2^{-1}) \varphi(z_2x^{-1})$   
 by local hom, so that nearby paths agree.

Compactness of  $D^2$  yields a finite number of small changes to get from  $p$  to  $q$ .  $\square$

Rest of proof: So define  $\varphi(g) = \varphi_p(g)$  (irrelevant which, since  $U$  simply connected)



Composing  $\varphi_p$  with  $\varphi_{p-h}$  get a path to  $gh$ . Using a time decomposition including  $h$ , we see that

$$\varphi(gh) = \varphi(gh)h^{-1} \varphi(h) = \varphi(g)\varphi(h)$$
 so it is a homomorphism.

Remark: Smoothness follows from smoothness near  $I$ , since  $\varphi$  near  $g$  is  $\varphi(g) \circ \varphi(\text{near } I)$  and left mult is smooth.  $\square$