

Recall: G a Lie group, we spend time computing $T_1 G$ b/c Ben said it was important.

(It's called the Lie algebra $\text{Lie } G = T_1 G \dots$)

Ex: $G = \text{GL}(n; \mathbb{R})$ open in $\text{Mat}(n; \mathbb{R})$ so $T_1 G = T_1 \text{Mat} = \text{Mat} \equiv \mathfrak{gl}(n; \mathbb{R}) = \text{Lie } \text{GL}(n; \mathbb{R})$

Ex: $G = \text{SL}(n; \mathbb{R}) = \det^{-1}(1)$ so $\text{Lie } \text{SL}_n \equiv \mathfrak{sl}_n = \ker(d\det)_1 = \{X \in \mathfrak{gl}_n \mid \text{tr } X = 0\}$

Was an exercise: $G = \text{SO}(n; \mathbb{R})$ so $\mathfrak{so}(n; \mathbb{R}) = \{X \in \mathfrak{gl}_n \mid X + X^T = 0\}$

Rank: $\text{tr } X = \text{tr } X^T$ so $\text{tr } X = 0$ so $X \in \mathfrak{sl}_n$ already.
 (derivative of orthogonal condition)

$\text{Lie } \text{O}(n; \mathbb{R}) = \text{Lie } \text{SO}(n; \mathbb{R})$. But not surprising since $\text{SO}(n; \mathbb{R})$ is connected composed of identity, so some nbhd of I .

$G = \text{SU}(n) \subset \text{GL}(n; \mathbb{C})$ so $\mathfrak{su}(n) = \{X \in \mathfrak{gl}_n(\mathbb{C}) \mid X + X^* = 0\}$

Ben had claimed: $\forall X \in T_1 G \exists$ one parameter subgroup $\varphi_X = \varphi: \mathbb{R} \rightarrow G$ st

$X = \left. \frac{d}{dt} \right|_{t=0} \varphi(t)$, i.e. $X = (d\varphi_0)(\cdot 1)$ (unit tangent vector in \mathbb{R} at origin.)

For matrix Lie groups like the above we now construct φ_X explicitly w/ the exponential map.

First \mathfrak{GL}_n , later in week the others. Work over \mathbb{R} or \mathbb{C} , your choice, well do \mathbb{C} .

§1 Defn + Basis

$e^z = \sum_{n \geq 0} \frac{z^n}{n!} = 1 + z + \frac{z^2}{2} + \dots$ absolutely convergent for all $z \in \mathbb{C}$.

So why not define $e^X = \sum \frac{X^n}{n!}$ for a matrix $X \in \mathfrak{gl}_n = \mathfrak{gl}(n; \mathbb{C})$.

Prop: $X \mapsto \sum \frac{X^n}{n!}$ is absolutely convergent $\forall X \in \mathfrak{gl}_n$. It is a smooth fn $\mathfrak{gl}_n \rightarrow \text{GL}_n$.

Why is e^X invertible?
 Soon...

Sketch: Consider the sum matrix entry by matrix entry.

Let $M \in \mathbb{R}$ be bigger than $|x_{ij}|$ the max entries of X . The entries of X^k are bounded by $n \cdot M^k$. Entries in X^k by $n^k \cdot M^k$.
 the sum $\sum \frac{n^k M^k}{k!}$ is bounded by $\sum \frac{(nM)^k}{k!}$ so it is absolutely convergent. \square

For more precision + a study of norms on matrices (the Hilbert-Schmidt norm) see Hall. (2)

Ex: $X = \begin{pmatrix} a & 0 \\ 0 & c \end{pmatrix}$ $X^2 = \begin{pmatrix} a^2 & 0 \\ 0 & c^2 \end{pmatrix} \dots$ $e^X = \begin{pmatrix} e^a & 0 \\ 0 & e^c \end{pmatrix}$ Diagonal = Easy.

Rmk: $\text{Tr} X = a + c = \text{sum of evales in general}$

$e^{\text{Tr} X} = e^{\sum \lambda_i} = \prod e^{\lambda_i} = \det e^X = \text{product of exponential eigenvalues.}$

Ex: $X = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ $X^2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ $X^3 = 0$ $X^4 = 0$ Unlike e^z , e^X may be a finite sum!

$e^X = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ More interesting: $e^{tX} = \begin{pmatrix} 1 & t \\ 0 & 1 \end{pmatrix}$ Nilpotent = Easy

Rmk: $\text{Tr} X = 0$ $\det e^X = 1 \Rightarrow e^{\text{Tr} X} = \det e^X$.

Properties: (1) P invertible then $P e^X P^{-1} = e^{P X P^{-1}}$.

Pf: $P \left(\frac{X^n}{n!} \right) P^{-1} = \frac{(P X P^{-1})^n}{n!}$ so true termwise.

(2) $(e^X)^T = e^{X^T}$ $(e^X)^* = e^{(X^*)}$ $\overline{e^X} = e^{\overline{X}}$ Same proof.

(3) If X and Y commute then $e^X e^Y = e^{X+Y}$

Pf: $(I + X + \frac{X^2}{2!} + \dots)(I + Y + \frac{Y^2}{2!} + \dots) = \sum_{k,l} X^k Y^l \frac{1}{k!l!} = \sum_{m=0}^{\infty} \sum_{k+l=m} \frac{X^k Y^l}{k!l!} = \sum_{m=0}^{\infty} \frac{X^m Y^m}{m!} = \sum_{m=0}^{\infty} \frac{(X+Y)^m}{m!}$

b/c X, Y commute! $\rightarrow \sum_{m=0}^{\infty} \frac{1}{m!} (X+Y)^m$

Rmk: In general, $e^X e^Y = e^{X+Y + \frac{1}{2}(XY-YX) + \dots}$

Baker-Campbell-Hausdorff formula Later.

Exercise: $X = \begin{pmatrix} t & 0 \\ 0 & 0 \end{pmatrix}$ $Y = \begin{pmatrix} 0 & s \\ 0 & 0 \end{pmatrix}$ $e^X e^Y = \begin{pmatrix} e^t & s e^t \\ 0 & 1 \end{pmatrix}$ $e^{X+Y} = \begin{pmatrix} e^t & s \frac{e^t - 1}{t} \\ 0 & 1 \end{pmatrix}$

Consequences: (4) $\varphi_X: t \mapsto e^{tX}$ is a homom $\mathbb{R} \rightarrow \mathcal{GL}(n, \mathbb{C})$ (3)
 b/c tX, sX commute for $t, s \in \mathbb{R}$. Also $(e^{tX})^{-1} = e^{-tX}$, so invertible.

Note $\frac{d}{dt} \Big|_{t=0} \varphi_X(t) = X$, realizing Beil's claim \star

Rule: (Soon) Every 1-param family $\mathbb{R} \rightarrow \mathcal{GL}(n, \mathbb{C})$ has the form e^{tX} for some $X \in \mathfrak{gl}(n)$

(5) $\det e^{tX} = e^{t \operatorname{Tr} X} \quad \forall X.$

Pf 1: X diagonalizable $\Rightarrow PXP^{-1} = D \quad \operatorname{Tr} X = \operatorname{Tr} D$
 $P e^{tX} P^{-1} = e^{tD} \quad \det e^{tX} = \det e^{tD}$ by before

Diagonalizable are dense in $\mathcal{GL}(n, \mathbb{C})$! (If evales are distinct, then diagonalizable)
 so continuity gives general case.

Pf 2: By Jordan normal form, up to conjugation,

$$PXP^{-1} = \begin{pmatrix} \lambda & & & 0 \\ & \lambda & & 0 \\ & & \ddots & \\ & & & \lambda \\ & & & & \mu & & \\ & & & & & \mu & \\ & & & & & & \nu & \\ & & & & & & & \nu & \\ & & & & & & & & \ddots & \\ & & & & & & & & & \nu \end{pmatrix} = \begin{pmatrix} \lambda & & & \\ & \lambda & & \\ & & \ddots & \\ & & & \lambda \\ & & & & \mu & & \\ & & & & & \mu & \\ & & & & & & \nu & \\ & & & & & & & \nu & \\ & & & & & & & & \ddots & \\ & & & & & & & & & \nu \end{pmatrix} + \begin{pmatrix} 0 & & & \\ & 0 & & \\ & & \ddots & \\ & & & 0 \\ & & & & 0 & & \\ & & & & & 0 & \\ & & & & & & 0 & \\ & & & & & & & 0 & \\ & & & & & & & & \ddots & \\ & & & & & & & & & 0 \end{pmatrix}$$

S diagonal (izable)
 N nilpotent ($\Leftarrow P^{-1}NP$)

$SN = NS$!!! so $e^{S+N} = e^S e^N$.
 even to check for diagonalizable + nilpotent separately.

Rule: Jordan Form is the most effective way to compute matrix exponentials.

Compute P, S, N if $PXP^{-1} = S+N$ \leftarrow math 342, find eigenvectors.

There will be some exercises.

§2 Matrix Log

e^z not injective, $\log(z)$ not globally defined

e^z injective on nbhd of 0, $\log(z)$ inverse on nbhd of 1.

(4)

$$\log(z) = \sum_{n \geq 1} (-1)^{n+1} \frac{(z-1)^n}{n} \quad \text{absolutely converges for } |z-1| < 1.$$

Prop: $\log(X) \equiv \sum_{n \geq 1} (-1)^{n+1} \frac{(X-I)^n}{n}$ absolutely converges in nbhd of I , gives smooth inverse to e^X .

(Again, for "radius of convergence" details see Hall.)

Pf Sketch: (1) Show for X diagonal (this is just the e^x number fact for each diagonal term)

(2) $\Rightarrow X$ diagonalizable b/c $P \log(X) P^{-1} = \log(PXP^{-1})$

(3) Diagonal done

Cor: $\exp: T_I \mathbb{C}^n = \mathbb{C}^n \rightarrow \mathbb{C}^n$ is a local diffeo from nbhd of $0 \in \mathbb{C}^n$ to nbhd of $I \in \mathbb{C}^n$

(NOT a homeomorphism though, b/c $e^{x+2\pi i} \neq e^x$.)

Prob: This will be true for every $G \subset \mathbb{C}^n$, and even every Lie group w/ the appropriate defn of exp.

That's enough for one day.

— Didn't do this stuff!

33 Matrix Lie Groups

Def: A matrix Lie group is a closed subgroup $G \subset GL(n; \mathbb{R})$ or \mathbb{C} . (5)

(The closed condition is equivalent to the embedding condition for groups - more on this eventually.)

Prevents stuff like $\begin{pmatrix} e^{it} & 0 \\ 0 & e^{nit} \end{pmatrix}$ for $n \in \mathbb{R} \setminus \mathbb{Q}$, this is dense in $\begin{pmatrix} S^1 & \\ & S^1 \end{pmatrix}$

but as a group \cong to \mathbb{R} .

Prop (5.2 in Bomp): $\mathbb{R} \rightarrow GL_n$ is tangent to G at I (i.e. $X \in T_I G$)
 $t \mapsto e^{tX}$

$$\iff e^{tX} \in G \quad \forall t \in \mathbb{R} \quad !!!$$

Pf: \Leftarrow is clear. \Rightarrow sparse not. $\exists s \in \mathbb{R}, e^{sX} \notin G$. $e^{sX} \in G$.

By Urysohn can choose $\phi_0: GL_n \rightarrow \mathbb{R}_{\geq 0}$ compactly supported, $\int_{GL_n} \phi_0 = 1$
 (a "bump" function) s.t. $\phi_0 = 0$ on G $\phi_0 = 1$ on e^{sX} .

Then define $\phi: GL_n \rightarrow \mathbb{R}_{\geq 0}$ $\phi(h) = \int \phi_0(hg) dg$ \leftarrow left Haar measure on G .

Then ϕ is invariant on cosets GL_n/G , that is $\phi(hg') = \phi(h)$ for $g' \in G$

$$\text{b/c } \phi(hg') = \int \phi_0(hg'g) dg = \int \phi_0(hg'') dg'' \leftarrow \text{by left invar.}$$

Also $\phi(I) = 0$ since $\phi_0 = 0$ on G , but $\phi(e^{sX}) \neq 0$

Let $f: \mathbb{R} \rightarrow \mathbb{R}$ $t \mapsto \phi(e^{tX})$. Then $f'(t) = \lim_{u \rightarrow 0} \frac{\phi(e^{tX} e^{uX}) - \phi(e^{tX})}{u} = \lim_{u \rightarrow 0} \frac{\phi(e^{tX} g_u) - \phi(e^{tX})}{u}$

for $g_u \in G$ close to e^{uX} (since e^{uX} is tangent, these limits agree) \parallel
 $0, \forall t.$

$\Rightarrow f$ is a constant function \times .

So get alternate defn of $T_I G \equiv \text{Lie } G: \text{Lie } G = \{X \in gl_n \mid e^{tX} \in G \forall t\}$

Note! $T_I G$ is a v.s. but this condition ^{does} NOT obviously give a v.s. b/c $e^{X+Y} \neq e^X e^Y$.

That it is a v.s. will follow from the Lie Product Theorem (soon).

Rmk! Really need the $\forall u$ that defines $\text{Lie } G = \{X \mid e^{tX} \in G\}$. (6)

Cor! $\exp: \text{Lie } G \rightarrow G$ is a local diffeomorphism near 0 , w/ inverse \log .

Pf! True of \exp , just didn't know image of $\text{Lie } G$ was in G before.

Now we get yet another computation of $\text{Lie } G$.

Ex! $\text{Lie } SO_n = \{X \mid \det e^{tX} = 1 \ \forall t\}$ $\det e^{tX} = 1 \Rightarrow$ ~~$e^{\text{tr}(tX)} = 1$~~
 $e^{\text{tr}(tX)} = 1$

$$\Leftrightarrow \text{tr}(tX) \in 2\pi\mathbb{Z}, \ \forall t \Leftrightarrow \text{tr}(X) = 0. \quad \checkmark$$

Ex! $\text{Lie } SO_n = \{X \mid (e^{tX})(e^{tX})^T = I\}$. Apply $\frac{d}{dt}\big|_{t=0}$ to get

$$0 = (Xe^{tX})(e^{tX})^T + (e^{tX})(X^T e^{tX}) \big|_{t=0} = X + X^T$$

so $X + X^T = 0$.

Conversely if $X + X^T = 0$ then $[X, X^T] = 0$ (not usually true) and

$$(e^{tX})(e^{tX^T}) = e^{t(X+X^T)} = I, \ \forall t. \quad \checkmark$$

Rmk! $X + X^T = 0 \Rightarrow \text{tr } X = 0$ b/c $\text{tr } X = \text{tr } X^T$. So get " \mathbb{Z} " condition automatically.

$$\text{Lie } SO_n = \text{Lie } O_n.$$

Ex! B a nonsingular form. Or exercises you shared $SO(B) = \{A \in GL_n \mid A^T B A = B\}$

$$\text{Then } \text{Lie } SO(B) = \{X \mid (e^{tX})^T B (e^{tX}) = B \ \forall t\} \xrightarrow{\frac{d}{dt}\big|_{t=0}} \underline{X^T B + B X = 0}.$$

Exercise! ~~$\text{Lie } Sp(2n)$~~ $\text{Lie } Sp(2n)$.

34 Key Consequences (1) $g \in G$ $X \in \text{Lie } G \cong T_{\mathbb{I}}G$, both viewed as living in Mat $_n$ (7)

then $gXg^{-1} \in \text{Lie } G$. We have homomorphism $G \rightarrow \text{GL}(\text{Lie } G)$
 $g \mapsto \text{conj by } g$
 called the Adjoint action.

PF 1: Conj by g is automorphism of G sending $I \mapsto I$, so its derivative is a map $T_{\mathbb{I}}G \rightarrow T_{\mathbb{I}}G$. Computation in $T_{\mathbb{I}}\text{GL}_n = \mathfrak{gl}_n$ showed that $d(\text{conj by } g)$ is realized by (conj by g) on \mathfrak{gl}_n . \square

PF 2: $e^{t(gXg^{-1})} = g e^{tX} g^{-1} \in G \quad \forall t$ \square

(2) $X, Y \in \text{Lie } G \Rightarrow [X, Y] = XY - YX \in \text{Lie } G$.

PF 2: If $e^{tX} \in G$, $Y \in \text{Lie } G$ then $e^{tX} Y e^{-tX} \in \text{Lie } G \subset \mathfrak{gl}_n, \forall t$.

(If $f: \mathbb{R} \rightarrow V \subset \mathbb{R}^N$ is a path in \mathbb{R}^N whose image lies in V , then $\frac{df}{dt} \Big|_{t=0}$ is a path in \mathbb{R}^N also lying in V)

Thus $\frac{df}{dt} \Big|_{t=0} \in \text{Lie } G$, for $f(t) = e^{tX} Y e^{-tX}$, $\frac{df}{dt} = X e^{tX} Y e^{-tX} + e^{tX} Y (-X) e^{-tX}$

At $t=0$ get $XY - YX$.

So $[X, \cdot] : \text{Lie } G \xrightarrow{\text{ad}} \text{End}(\text{Lie } G) = \mathfrak{gl}(\text{Lie } G)$ is a linear map. adjoint action

(3) In fact $\text{Ad}: G \rightarrow \text{GL}(\text{Lie } G)$

$\left. \begin{array}{l} \text{take derivative at } \mathbb{I} \end{array} \right\} d(\text{Ad})_{\mathbb{I}} = \text{ad}$.

$d(\text{Ad})_{\mathbb{I}} : \text{Lie } G \rightarrow \mathfrak{gl}(\text{Lie } G)$

PF: To compute $d(\text{Ad})_{\mathbb{I}}(X)$, take $\frac{d}{dt} \Big|_{t=0} \text{Ad}(e^{tX})$.

We computed above that this sends Y to $[X, Y]$. \square

§5 More properties of Matrix Exponentiation

(8)

① Thm (Lie Product Formula) $e^{x+y} = \lim_{n \rightarrow \infty} \left(e^{\frac{x}{n}} e^{\frac{y}{n}} \right)^n$.

[Cor] $\text{Lie } \mathfrak{G} = \{X \mid e^{tX} \in \mathfrak{G} \forall t\}$ is a v.s. when \mathfrak{G} is closed in \mathbb{Q}_n .

[Pf] $e^{t(x+y)} = \lim_{n \rightarrow \infty} \left(e^{\frac{tx}{n}} e^{\frac{ty}{n}} \right)^n$ is in $\mathfrak{G} \forall t$, if $X, Y \in \text{Lie } \mathfrak{G}$. \square

[Pf] Reall: $e^z = \lim_{m \rightarrow \infty} \left(1 + \frac{z}{m} \right)^m$. In fact, $e^z = \lim_{m \rightarrow \infty} \left(1 + \frac{z}{m} + C_m \right)^m$

(Sketch) For any sequence C_m w/ $|C_m| < \frac{K}{m^2}$ for some K .

Now $e^x e^y = \left(1 + \frac{x}{m} + \frac{x^2}{2m^2} + \dots \right) \left(1 + \frac{y}{m} + \frac{y^2}{2m^2} + \dots \right) = 1 + \frac{x+y}{m} + o\left(\frac{1}{m}\right)$. \square
 (For rigorous version see Hall.)

② Thm: Every continuous homom. $\mathbb{R} \xrightarrow{f} \mathbb{Q}_n$ has the form $t \mapsto e^{tX}$ for some $X \in \mathfrak{gl}_n(\mathbb{C})$.

[Pf] (a) Show f is smooth. Then let $X = \frac{df}{dt} \Big|_{t=0}$. (b) Show $e^{tX} = f(t)$.

(a) Let ψ be a smooth bump function on \mathbb{R} near 0, and define $g(t) = \int_{\mathbb{R}} f(t+s)\psi(s) ds \in \mathbb{Q}_n$ Matrix.
 $= \int_{\mathbb{R}} f(u)\psi(u-t) du$. Then $\frac{dg}{dt}$ only involves $\frac{df}{dt}$, so g is smooth. (convolution trick)

But $f(t+s) = f(t)f(s) \Rightarrow g(t) = f(t) \int_{\mathbb{R}} f(s)\psi(s) ds$.

Since ψ bump near 0, $\int_{\mathbb{R}} f(s)\psi(s) ds$ is near I , so invertible matrix A .

$g(t) = f(t)A \Rightarrow f(t)$ smooth too!

(b) $f(t) = I + tX + o(t^2)$. For fixed t , let $C_m = f\left(\frac{t}{m}\right) - \left(I + \frac{tX}{m} \right)$

Then $|C_m| < \frac{K}{m^2}$ and $\lim_{m \rightarrow \infty} \left(1 + \frac{tX}{m} + C_m \right)^m = e^{tX}$

$\lim_{m \rightarrow \infty} f\left(\frac{t}{m}\right)^m = \lim_{m \rightarrow \infty} f\left(\frac{t}{m}\right) = f(t)$.

③ Thm: $\exp: \mathfrak{g}_\mathbb{R} \rightarrow G_\mathbb{R}$ is surjective. (Want proof, see exercises) ④

Rank 1: \log is NOT the "inverse".
the unit one, not negative

Rank 2: NOT true for all GCGLN.

However: Thm: $\exp: \mathfrak{L} \mathcal{G} \rightarrow \mathcal{G}$ is surjective when GCGLN is abelian and connected.

Pf: ~~It~~ Clearly \exp surjects onto a nbhd U of $1 \in \mathcal{G}$, where it is a local diffeo.

Let $U^k = \{g_1 g_2 \dots g_k \mid g_i \in U\}$. Then \exp surjects onto U^k , b/c

$e^x e^y = e^{x+y}$! Since X, Y commute...

Interjection: I said \mathcal{G} abelian, not $[X, Y] = 0 \forall X, Y \in \mathfrak{L} \mathcal{G}$!

But $[X, \cdot] = \frac{d}{dt} \Big|_{t=0} (\text{conj by } e^{tX})$, and conj by e^{tX} is a ~~field~~ identity, not ~~field~~

Interjection: I said \mathcal{G} abelian, not $e^{tX} g e^{-tX} = g \forall g \in \mathcal{G}, X \in \mathfrak{L} \mathcal{G}$!

But: $g e^{tY} g^{-1} = \frac{d}{dt} \Big|_{t=0} (g e^{tY} g^{-1}) = \frac{d}{dt} \Big|_{t=0} (e^{tY}) = Y$.

So we've deduced: If \mathcal{G} is abelian then $[X, Y] = 0 \forall X, Y \in \mathfrak{L} \mathcal{G}$

and $g e^{tY} g^{-1} = e^{tY} \forall g \in \mathcal{G}$.

Now any $g \in \mathcal{G}$ is in some U^k . After all, \exists path $[0, 1] \rightarrow \mathcal{G}$ from identity to g .

~~$p^{-1}(U^k)$ is a collection of open sets in $[0, 1]$, each strictly larger than the last, but no limit points.~~

Each mult by U gives some positive distance up the path. Let's do this explicitly.

Define U_t for $t \in [0, 1]$ to be $p^{-1}(U \cdot p(t))$. $U \cdot p(t)$ open (mult is a diffeo) so U_t open.

Hence $\{U_t\}$ is an open cover of $[0, 1]$, so it has a finite subcover. $U_{t_1} \cup \dots \cup U_{t_k} = [0, 1]$

If U_{t_1} and U_{t_2} intersect then $p(s) \in U_{t_1} \cap U_{t_2}$, since if $r \in U_{t_1} \cap U_{t_2}$ then

$p(s) = u_1 \cdot p(t_1) \quad p(t_2) = u_2 \cdot p(t_1)$.

So $p(1) \in U^{2k} \cdot p(0)$. Why? Draw graph where t_i and t_j connected if $U_{t_i} \cap U_{t_j} \neq \emptyset$. If graph not connected then get a disconnect of $[0,1]$.

So graph connected, and can get all vertices in a path of length $\leq \# \text{ vertices} - 1$.
 But then if $0 \in U_{t_1}$, $1 \in U_{t_k}$ then $p(t_1) \in U^{2(k-1)} p(t_2)$, $p(0) \in U \cdot p(t_1)$, $p(1) \in U \cdot p(t_k)$

(Many parts of this proof will return, hence the explicit version...)

§6 BCH formula $e^{X+Y} \neq e^X e^Y$ in general. So what is $e^X e^Y$?

$$e^{X+Y} = \left(I + X + \frac{X^2}{2} + \dots \right) \left(I + Y + \frac{Y^2}{2} + \dots \right)$$

$$= I + (X+Y) + \left(\frac{X^2}{2} + XY + \frac{Y^2}{2} \right) + \dots$$

$$e^{X+Y} = \left(I + (X+Y) + \frac{(X+Y)^2}{2} + \dots \right) = \left(I + (X+Y) + \frac{X^2 + XY + YX + Y^2}{2} + \dots \right)$$

difference in degree 2 is $\frac{XY - YX}{2} = \frac{[X, Y]}{2}$.

$$e^{X+Y + \frac{[X, Y]}{2}} = \left(\underbrace{I + (X+Y)}_{\text{linear}} + \underbrace{\frac{(X+Y)^2}{2} + \frac{[X, Y]}{2}}_{\text{quadratic}} + \text{higher terms} \right)$$

Thm (Baker-Campbell-Hausdorff formula):

$$e^X e^Y = e^{X+Y + \frac{1}{2}[X, Y] + \frac{1}{12}[X, [X, Y]] - \frac{1}{12}[Y, [X, Y]] + \dots}$$

Computable coeffs but not a nice formula

which, for fixed X (resp. Y), converges for Y (resp. X) in a neighborhood of 0.

Perhaps better to replace X, Y with tX, tY and compute the t^N terms of the power series.

For many more details see Hall. Exercise: Compute those $\frac{1}{12}, -\frac{1}{12}$ part.

If you don't know $e^X e^Y$, why do you care?

This expresses $e^X e^Y$ solely in terms of Commutators of X and Y . !!!

In that degree 2 computation, the difference didn't need to be a multiple of $[X, Y]$.

If could also have X^2, Y^2 terms, but it doesn't! 1D made 4D

For degree 3 $X^3, XY, YX^2, XYX, XY^2, Y^2X, YXY, Y^3$ 8Dim

$[X, [X, Y]]$, $[Y, [X, Y]]$ 2Dim.

Very "lucky" that only need commutators.

* Idea *: Commutators on $\text{Lie } G$ completely determine multiplication (near identity) in G .

§7 The Big ~~Picture~~ ^{Question}

Three related things:

- ① Homomorphisms (smooth) of Lie groups: $\varphi: G \rightarrow H$
- ② Local homomorphisms of Lie groups: $\varphi: U \rightarrow H$, U a nbhd of identity in G
 s.t. $\varphi(x)\varphi(y) = \varphi(xy)$ when $x, y, xy \in U$.
- ③ Linear maps of Lie algebras which preserve commutators
 $f: \text{Lie } G \rightarrow \text{Lie } H$
 $f([X, Y]) = [f(X), f(Y)]$.



Main example of interest. A smooth rep. is a smooth homom $\varphi: G \rightarrow GL(V)$

then $d\varphi: \mathfrak{g} = \text{Lie } G \rightarrow \mathfrak{gl}(V)$
 Given $d\varphi$, when can I find φ ? Is it unique?

Reps of Lie Grps \iff Reps of Lie algebras?
 Diff topology, smoothness, nasty \iff Linear algebra, relatively easy!!