

## Homework 6

Due: February 18, 2013

---

26. 6.9

27. 6.12

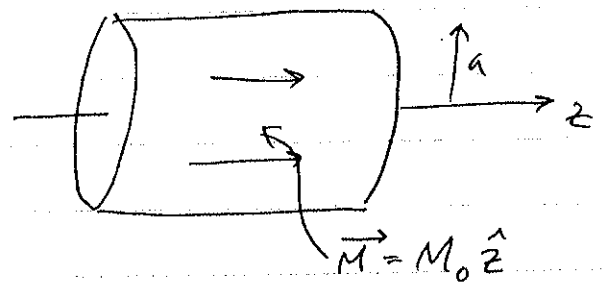
28. 6.16

29. 6.18

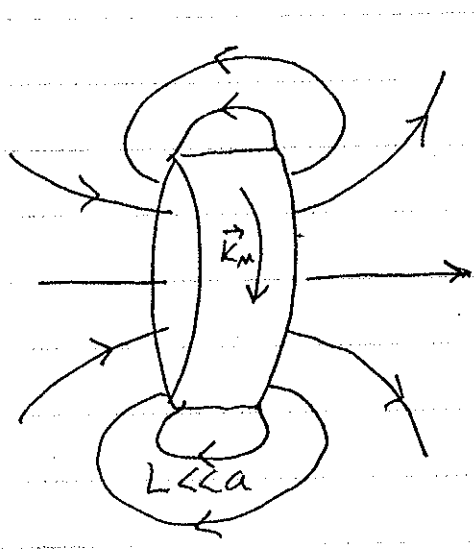
30. 6.20

31. 6.26

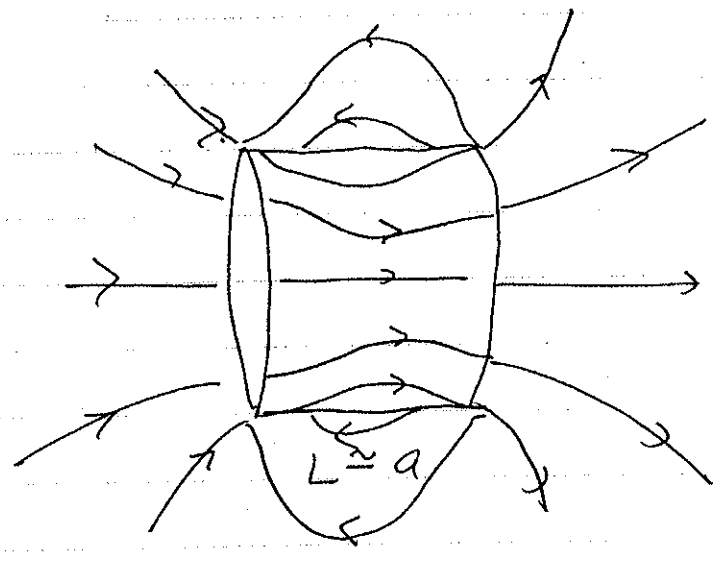
29. Problem 6.9



a)  $\vec{J}_m = \nabla \times \vec{M} = 0$  ,  $\vec{K}_m = \vec{M} \times \hat{S} = M_0 \hat{\phi}$

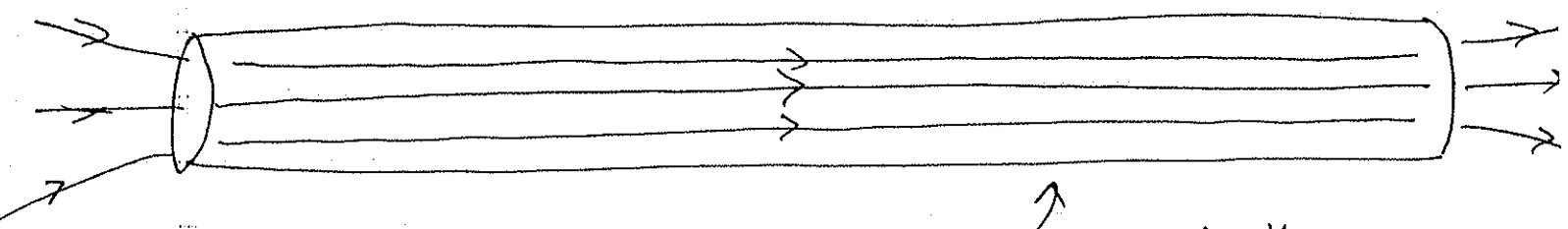


resembles wire loop



resembles torus

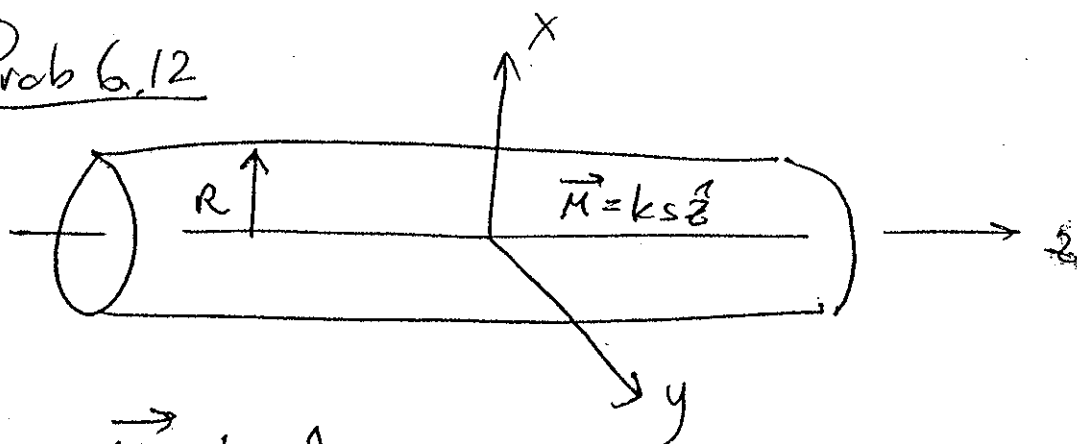
weak external  $\vec{B}$



resembles an infinite solenoid

$L \gg a$

Prob 6.12



$$\vec{M} = ks \hat{z} \rightarrow \vec{J}_M = \nabla \times \vec{M}$$

$$(i) \vec{J}_M = \nabla \times \vec{M} = -k \hat{\phi}$$

$$(ii) \vec{K}_M = \vec{M} \times \hat{s} \text{ at } s=R$$

$$= kR \hat{\phi}$$

Find  $\vec{B}$  using 2 methods

$$b) \nabla \times \vec{H} = \vec{J}_f \rightarrow \oint \vec{H} \cdot d\vec{\ell} = \int \vec{J}_f \cdot d\vec{S}$$

$$(i) H_{\phi} 2\pi s = 0 \rightarrow \boxed{H_{\phi} = 0} \quad \begin{array}{l} \int_{z} d\vec{\ell} \\ \int_{z} \vec{J}_f \cdot d\vec{S} \end{array}$$

$$(ii) -H_z \Delta z + H_z(z=0) \Delta z = 0 \quad \int_{z} \vec{H} \cdot d\vec{\ell}$$

$$\rightarrow H_z = H_z(z=0) \equiv \text{constant}$$

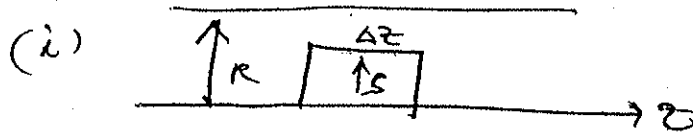
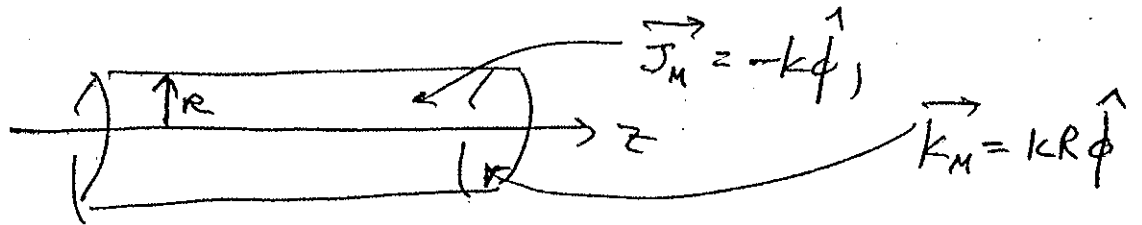
$$\text{if } H_z \rightarrow 0 \text{ at } z = \infty \rightarrow \boxed{H_z = 0}$$

$$\text{Now, } \vec{B} = \mu_0 \vec{H} + \mu_0 \vec{M}$$

$$\rightarrow \vec{B} = \begin{cases} 0, & s > R \\ \mu_0 ks \hat{z}, & s < R \end{cases}$$

$$a) \vec{\nabla} \times \vec{B} = \mu_0 \left[ \vec{J}_f + \vec{J}_M \right] = \mu_0 \vec{J}_M$$

$$\rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 \int \vec{J}_M \cdot d\vec{S}$$



$$\oint \vec{B} \cdot d\vec{l} = -B_z \Delta z + B_z(z=0) \Delta z$$

$$= \mu_0 \oint \vec{J}_M \cdot d\vec{S}$$

$$= \mu_0 \oint (-k dz ds)$$

$$\rightarrow (B_z + B_z(z=0)) \Delta z = -\mu_0 k \Delta z s \rightarrow \boxed{B_z = \mu_0 k s \hat{z}}$$

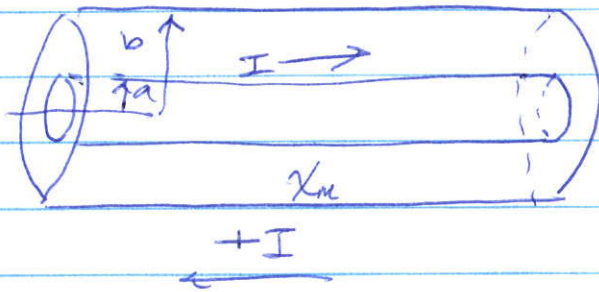


$$\oint \vec{B} \cdot d\vec{l} = -B_z(s > R) \Delta z + B_z(s=0) \Delta z = \int \vec{J}_M \cdot d\vec{S}$$

$$= 0!$$

$$\rightarrow \boxed{B_z(s > R) = B_z(s=0) = 0}$$

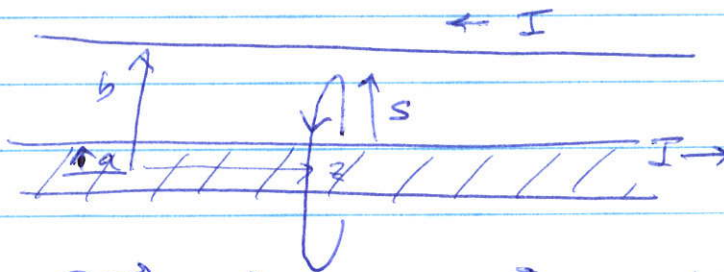
Prob 6.16



Two cylinders separated by material of susceptibility  $\chi_m$ . A current flows down the inner cylinder, magnitude  $I$ , and returns on the outer surface.

a) Find the field in the region between  $a$  &  $b$ .

Find  $\vec{H}$ , because it depends only on the free current,  $I$ .



$$a) \oint \vec{H} \cdot d\vec{l} = \int \vec{J} \cdot d\vec{s} \Rightarrow H \int 2\pi s = I, \quad \vec{H} = \frac{I}{2\pi s} \hat{\phi}$$

$s = [a, b]$

$$b) \oint \vec{H} \cdot d\vec{l} = \int \vec{J} \cdot d\vec{s} \Rightarrow H \int 2\pi s = 0, \quad s > b$$

$$\Rightarrow \vec{H} = 0, \quad s > b$$

b) Find  $\vec{M}$  &  $\vec{J}_M$

$$\vec{M} = \chi_m \vec{H} = \begin{cases} \chi_m \frac{I}{2\pi s} \hat{\phi} & s = [a, b] \\ 0 & s > b \end{cases}$$

$$\vec{J}_M = \nabla \times \vec{M} = \frac{\chi_m I}{2\pi} \left[ 0 \hat{s} + 0 \hat{\phi} + (0) \hat{z} \right] = 0$$

$$\vec{K}_M = \vec{M} \times \hat{n}$$

$$= \begin{cases} \chi_m \left( \frac{I}{2\pi a} \right) (\hat{z}) & , s=a \\ \chi_m \left( \frac{I}{2\pi b} \right) (-\hat{z}) & , s=b \end{cases}$$

c) Find the field using  $\vec{J}_M$ ,  $\vec{K}_M$ , and  $I_s$

The total current at  $r=a$  is

$$I_a = I + \chi_m \frac{I}{2\pi a} \times 2\pi a = (1 + \chi_m) I$$

The total current at  $r=b$  is

$$I_b = -I - \chi_m \left( \frac{I}{2\pi b} \right) \times 2\pi b = -(1 + \chi_m) I$$

(i) In the region  $[a, b]$

$$B_\phi 2\pi s = \mu_0 \left[ + (1 + \chi_m) I \right]$$

$$\rightarrow \vec{B}_\phi = \frac{\mu_0 I}{2\pi s} \hat{\phi} = \vec{H}_0 = \frac{I}{2\pi s} \hat{\phi}$$

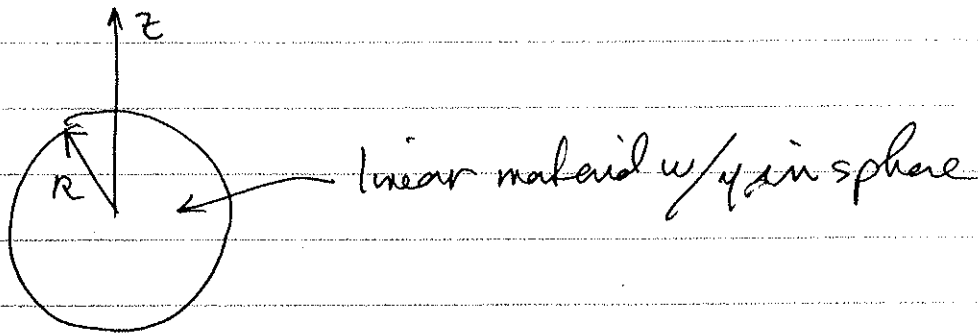
(ii)  $s > b$

$$B_\phi 2\pi s = \mu_0 [0] = 0$$

$$\rightarrow \vec{B}_\phi = 0, \quad s > b$$

33. Prob 6.18

↑ ↑ ↑ ↑  $\vec{B}_0$  at infinity =  $B_0 \hat{z}$



Find  $\vec{B}$  in the sphere.

a)  $\vec{\nabla} \times \vec{H} = \vec{J}_f = 0 \rightarrow \vec{H} = -\vec{\nabla} V_m$

$\vec{\nabla} \cdot \vec{B} \stackrel{\text{ad}}{=} \vec{\nabla} \cdot [\mu \vec{H}] = \vec{\nabla} \cdot \vec{H} = 0 \rightarrow \nabla^2 V_m = 0$

b) Boundary Conditions

(i) at  $\infty$ ,  $\vec{B} = \vec{B}_0 \rightarrow \vec{H}_0 = \frac{\vec{B}_0}{\mu_0}$  at infinity

$\rightarrow V_m(\infty) = -\frac{B_0}{\mu_0} z$

$= -\frac{B_0}{\mu_0} r \cos \theta$

The general sol<sup>n</sup> to the Laplace equation is

$$V_m = \sum_{l=0}^{\infty} \left( A_l r^l + \frac{B_l}{r^{l+1}} \right) P_l(\cos \theta)$$

To make  $V_m$  finite at the origin,

$$V_m^{<R} = \sum_{l=0}^{\infty} A_l r^l P_l(\cos \theta)$$

To make  $V_m \rightarrow -\frac{B_0}{\mu_0} r \cos \theta$  at  $\infty$

$$V_m^{>R} = \sum_{l=0}^{\infty} \frac{B_l}{r^{l+1}} P_l(\cos \theta) - \frac{B_0}{\mu_0} r \overbrace{P_1(\cos \theta)}^{\equiv \cos \theta}$$

Boundary conditions at surface of sphere

$$(a) V_m^{>R}(R) = V_m^{<R}(R)$$

$$\sum_{l=0}^{\infty} A_l R^l P_l(\cos \theta) = -\frac{B_0}{\mu_0} R P_1(\cos \theta) + \sum_{l=0}^{\infty} \frac{B_l}{R^{l+1}} P_l(\cos \theta)$$

$$\underline{l=0} \rightarrow A_0 = \frac{B_0}{R}$$

$$\underline{l=1} \rightarrow A_1 R = -\frac{B_0}{\mu_0} R + \frac{B_1}{R^2}$$

⋮

$$\underline{l=l} \rightarrow A_l R^l = \frac{B_l}{R^{l+1}} \rightarrow A_l = R^{-2l-1} B_l$$



$$(b) \vec{\nabla} \cdot \vec{B} = 0 \rightarrow \Delta B_r = 0 \rightarrow \mu H_r^< = \mu_0 H_r^> \quad (\text{at } r=R)$$

$$\rightarrow -\mu \left. \frac{\partial V_m^<}{\partial r} \right|_{r=R} = -\mu_0 \left. \frac{\partial V_m^>}{\partial r} \right|_{r=R}$$

$$\Rightarrow -\mu \left. \frac{\partial V_m^<}{\partial r} \right|_{r=R} = -\mu \left[ \sum_{l=0}^{\infty} l A_l^< R^{l-1} P_l \right]$$

$$-\mu \left. \frac{\partial V_m^>}{\partial r} \right|_{r=R} = -\mu_0 \left[ -\frac{B_0^>}{\mu_0} P_0 - \sum_{l=1}^{\infty} (l+1) \frac{B_l^>}{R^{l+2}} P_l \right]$$

$$\underline{l=0}: -\mu \times 0 = +\mu_0 \left[ \frac{B_0^>}{R^2} \right] \rightarrow B_0^> = 0 \rightarrow A_0^< = 0 \quad (\text{from a)}$$

$$\underline{l=1}: -\mu \left[ A_1^< \right] = \mu_0 \left[ \frac{B_0^>}{\mu_0} + 2 \frac{B_1^>}{R^3} \right] \leftarrow -\mu \left[ \frac{B_1^>}{R^3} - \frac{B_0^>}{\mu_0} \right]$$

$$\rightarrow \frac{B_1^>}{R^3} (2\mu_0 + \mu) = +\frac{\mu B_0^>}{\mu_0} - B_0^> = +B_0^> \left( \frac{-\mu + \mu_0}{\mu_0} \right)$$

$$\rightarrow \boxed{B_1^> = -\frac{B_0^> R^3}{\mu_0} \left( \frac{-\mu + \mu_0}{\mu + 2\mu_0} \right)}$$

$$\rightarrow A_1^< = -\frac{B_0^>}{\mu_0} - \frac{B_0^> R^3}{\mu_0 R^2} \left( \frac{-\mu + \mu_0}{\mu + 2\mu_0} \right)$$

$$A_1^< = -\frac{B_0}{\mu_0} \left( \frac{2\mu + 3\mu_0}{\mu + 2\mu_0} \right)$$

$$l=2: -2\mu A_2^< R = +3\mu_0 \frac{B_2^>}{R^4} \rightarrow A_2^< = -\frac{3\mu_0 B_2^>}{2\mu R^5}$$

$$\text{from (a)} \rightarrow B_2^> / R^5$$

$$\rightarrow B_2^> = 0 = A_2^<$$

∴ and so on

$$\rightarrow V_m(r, \theta) = \begin{cases} -\frac{B_0}{\mu_0} \left( \frac{2\mu + 3\mu_0}{\mu + 2\mu_0} \right) r \cos\theta, & r < R \\ -\frac{B_0 R^3}{\mu_0} \left( \frac{\mu + \mu_0}{\mu + 2\mu_0} \right) \frac{\cos\theta}{r^2} - \frac{B_0}{\mu_0} r \cos\theta, & r > R \end{cases}$$

$$\rightarrow \vec{H} = \begin{cases} \frac{B_0}{\mu_0} \left( \frac{2\mu + 3\mu_0}{\mu + 2\mu_0} \right) \hat{z}, & r < R \\ +\frac{B_0}{\mu_0} \hat{z} + \frac{B_0 R^3}{\mu_0} \left( \frac{\mu + \mu_0}{\mu + 2\mu_0} \right) \vec{\nabla} \left( \frac{\cos\theta}{r^2} \right), & r > R \end{cases}$$

for  $r < R$ ,  $\vec{B} = \mu \vec{H}$  and we have,

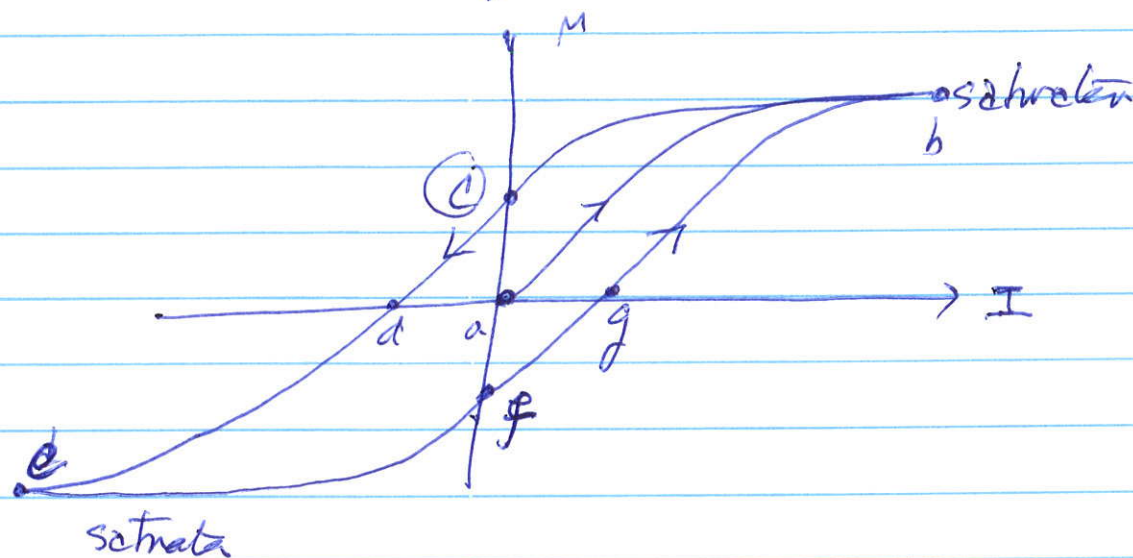
$$\vec{B}^<(r, \theta) = \frac{\mu}{\mu_0} B_0 \left( \frac{2\mu + 3\mu_0}{\mu + 2\mu_0} \right) \hat{z}$$

So, if  $\mu = \mu_0$  ( $\Rightarrow$  no magnetic material)

$$\rightarrow \vec{B}^<(r, \theta) = B_0 \hat{z}$$

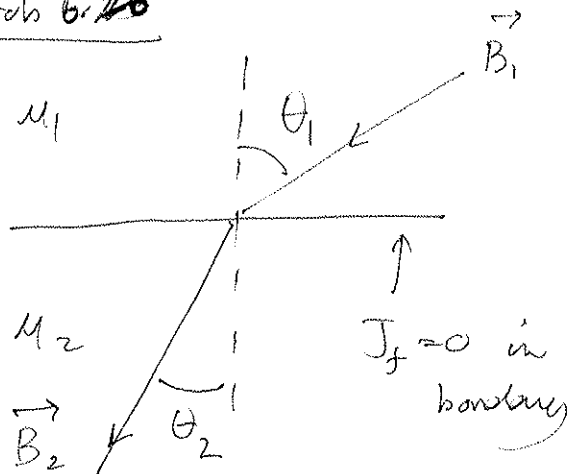
## Prob 6.20

How would you go about demagnetizing a permanent magnet at point  $e$  in the hysteresis loop? That is, how would you restore it to its original state w/  $\vec{M} = 0$  at  $\vec{I} = 0$ ?



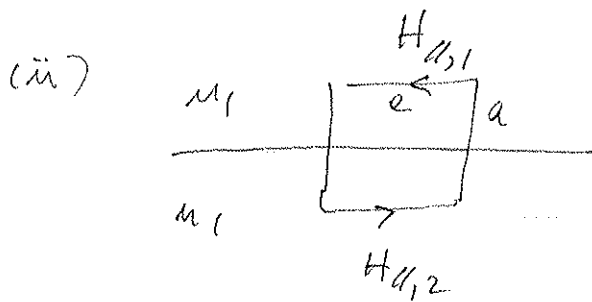
- heat it beyond Curie temperature
- hit it w/ a "hammer" or softly
- Continue to "decrease"  $I$  to push material to its coercive field and then shut off current (increase to 0) to return to axial state

Prob 6.26



Show that  $\frac{\tan \theta_2}{\tan \theta_1} = \frac{\mu_2}{\mu_1}$

(i)  $\Delta B_n = 0 \Rightarrow B_{1,\perp} = B_{2,\perp}$



$$\vec{\nabla} \times \vec{H} = 0, \text{ since } J_f = 0$$

$$\Rightarrow \oint \vec{H} \cdot d\vec{\ell} = 0$$

and so,

$$H_{||,1} l - H_{||,2} l = 0$$

$$H_{||,1} = H_{||,2}$$

and for a linear medium

$$\mu_1^{-1} B_{||,1} = \mu_2^{-1} B_{||,2}$$

(iii)  $\tan \theta_1 = \frac{B_{||,1}}{B_{\perp,1}}, \tan \theta_2 = \frac{B_{||,2}}{B_{\perp,2}}$

$$\frac{\tan \theta_2}{\tan \theta_1} = \frac{B_{||,2}}{B_{||,1}} \cdot \frac{B_{\perp,1}}{B_{\perp,2}} = \left( \frac{\mu_2}{\mu_1} \right) (1) = \frac{\mu_2}{\mu_1}$$